

Towards World-Scale Virtual Reality

Christian Holz (really: all the MSR collaborators and interns on these projects!) ETH Zürich



# VR spaces today

| desktop-scale | living-room scale | garage-scale |
|---------------|-------------------|--------------|
| small         | medium            | large        |

| desktop-scale | living-room scale | garage-scale | building | city |
|---------------|-------------------|--------------|----------|------|
| small         | medium            | large        |          | huge |

| desktop-scale | living-room scale     | garage-scale        | building                       | city |
|---------------|-----------------------|---------------------|--------------------------------|------|
| small         | medium                | large               |                                | huge |
|               |                       |                     |                                |      |
|               | controlled space, but | t limited dimension | unlimited sparbut but uncontro |      |

| desktop-scale | living-room scale     | garage-scale | building                   | city |
|---------------|-----------------------|--------------|----------------------------|------|
| small         | medium                | large        |                            | huge |
|               | controlled space, but |              | unlimited sparbut uncontro |      |



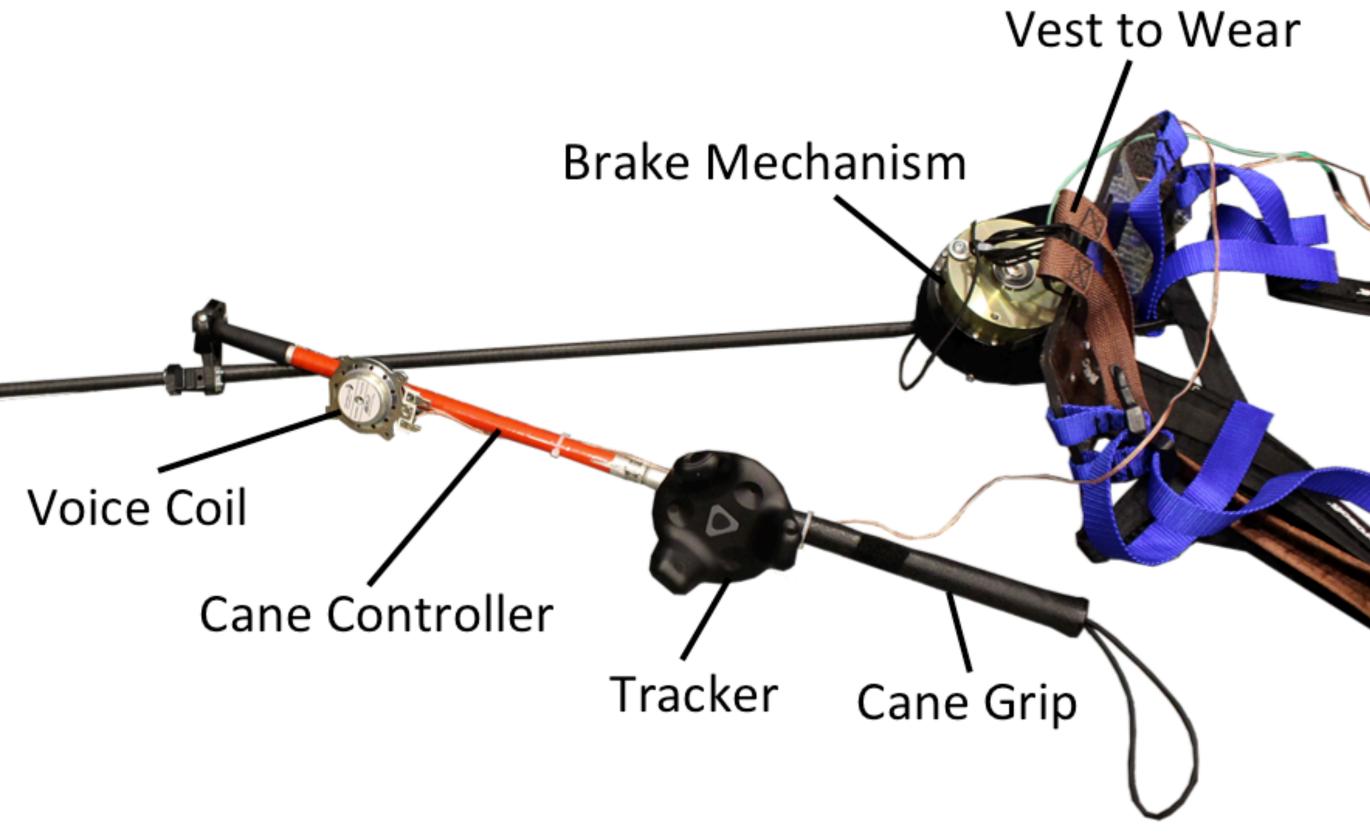




| desktop-scale | living-room scale    | garage-scale | building        | city |
|---------------|----------------------|--------------|-----------------|------|
| small         | medium               | large        |                 | huge |
|               | controlled space, bu |              | unlimited spar- |      |



## Canetroller



## orientation & mobility using a white cane

provides tactile and audio feedback

three cane techniques







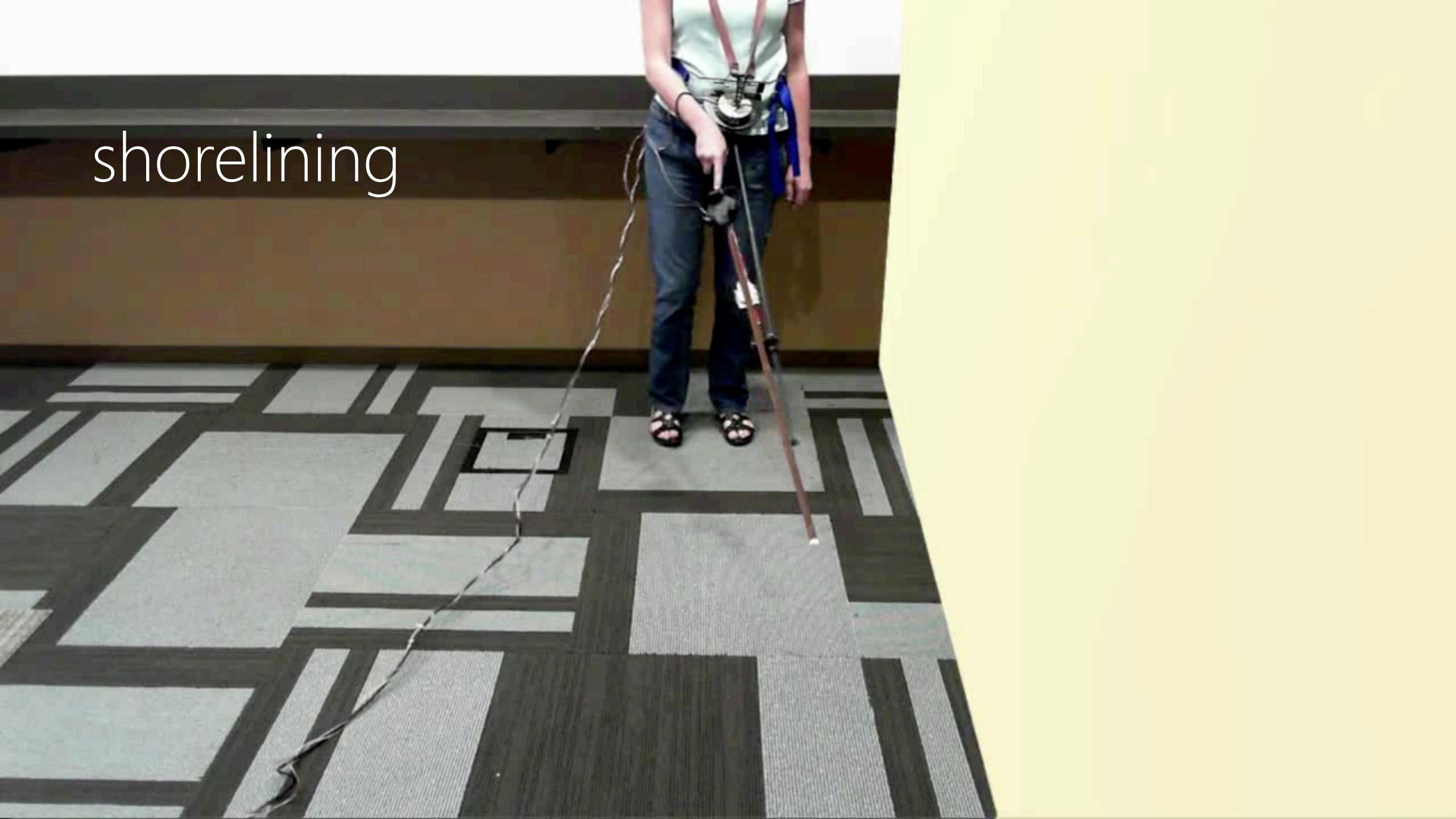
two-point touch

constant contact

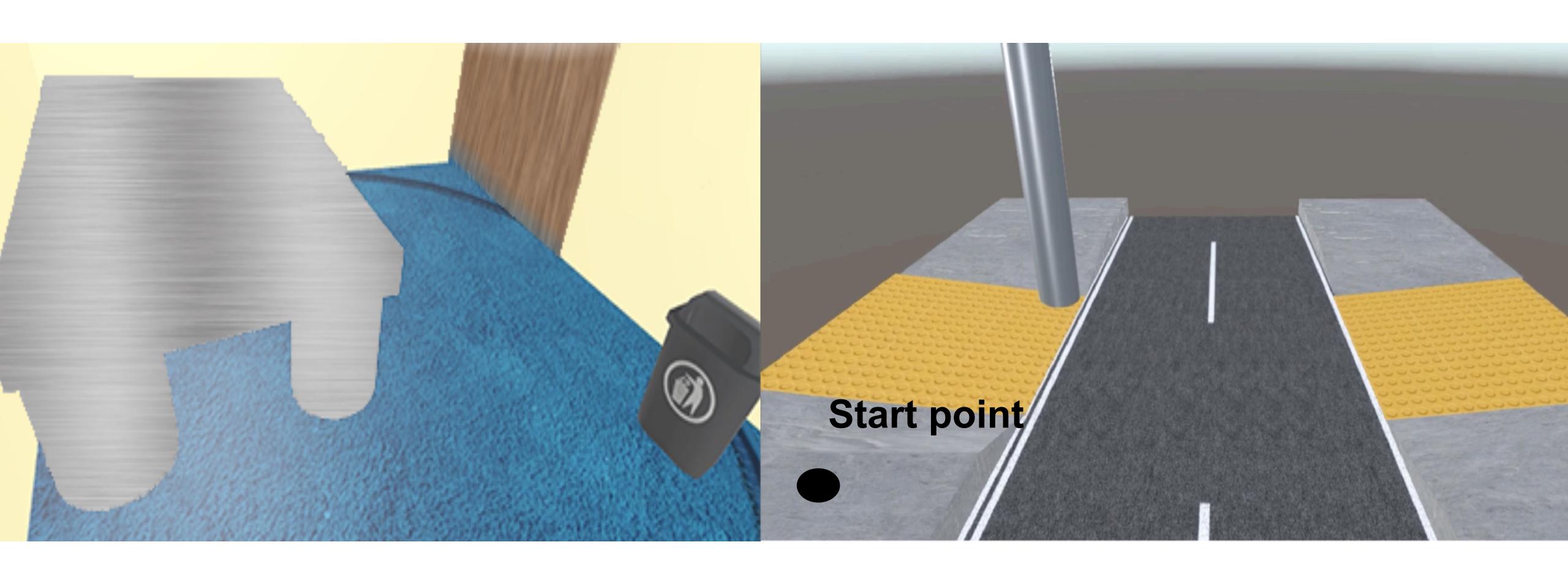
shorelining







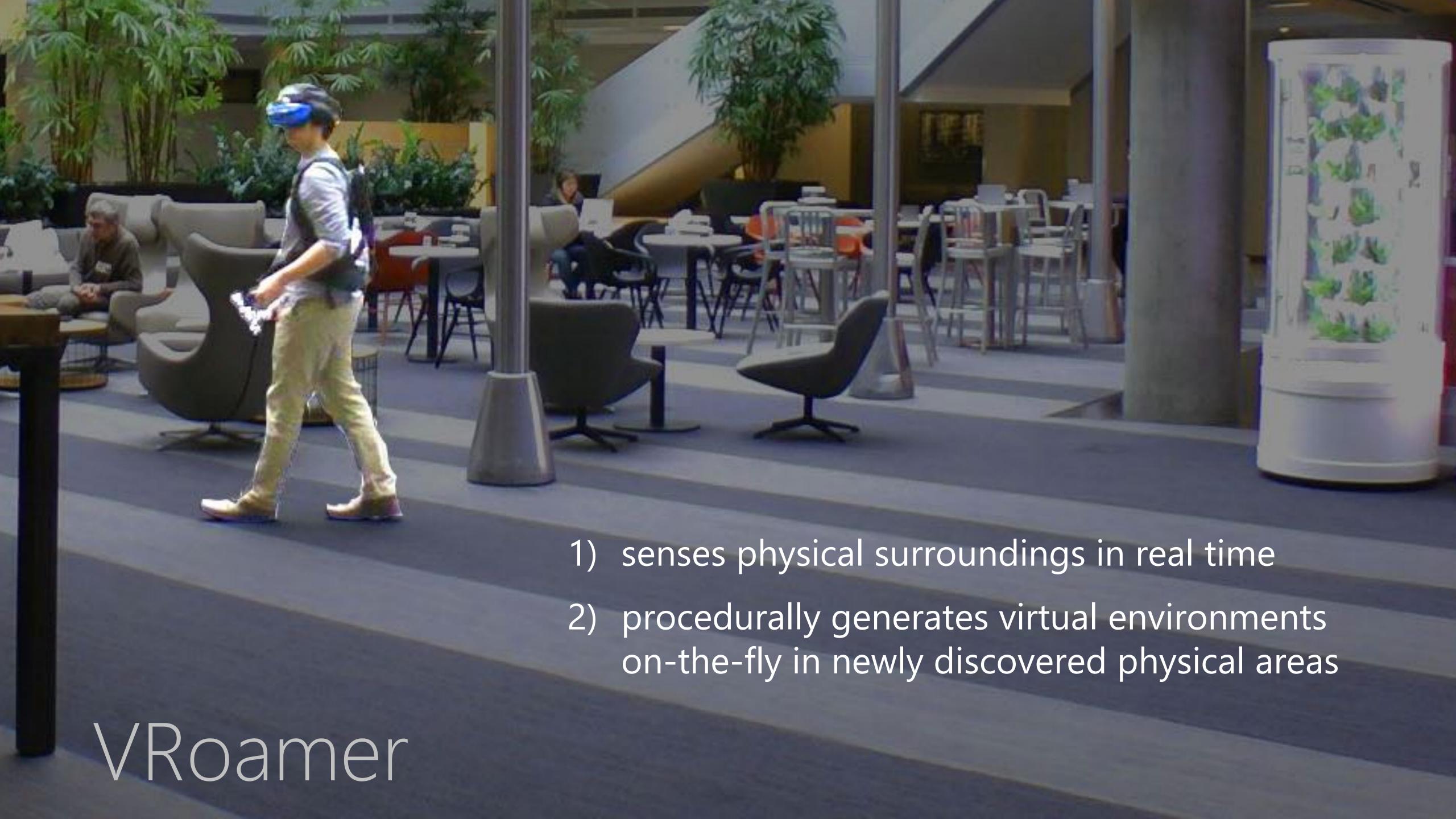
### indoor and outdoor VR scenes

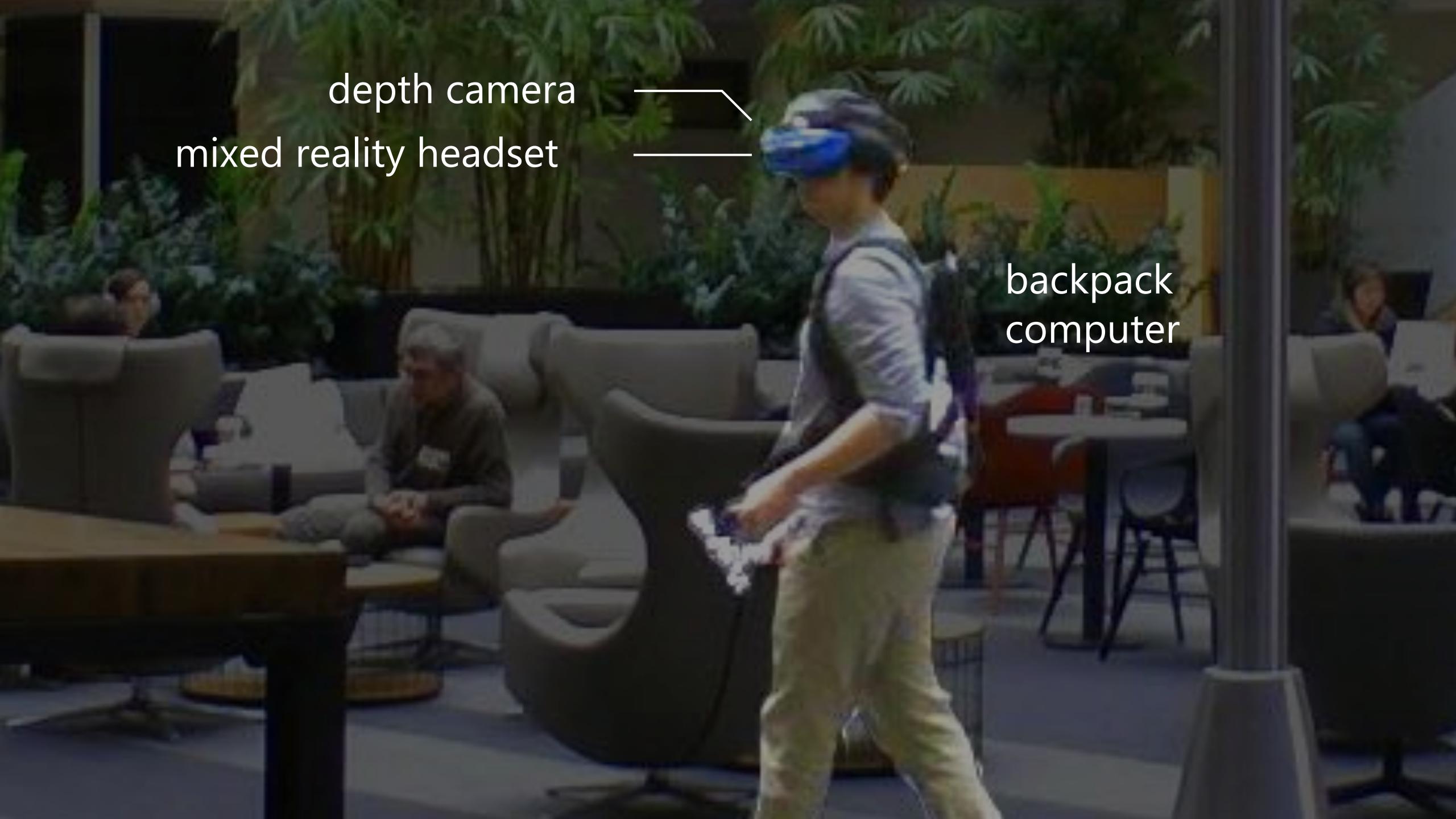


| desktop-scale | living-room scale     | garage-scale | building                   | city |
|---------------|-----------------------|--------------|----------------------------|------|
| small         | medium                | large        |                            | huge |
|               | controlled space, but |              | unlimited sparbut uncontro |      |





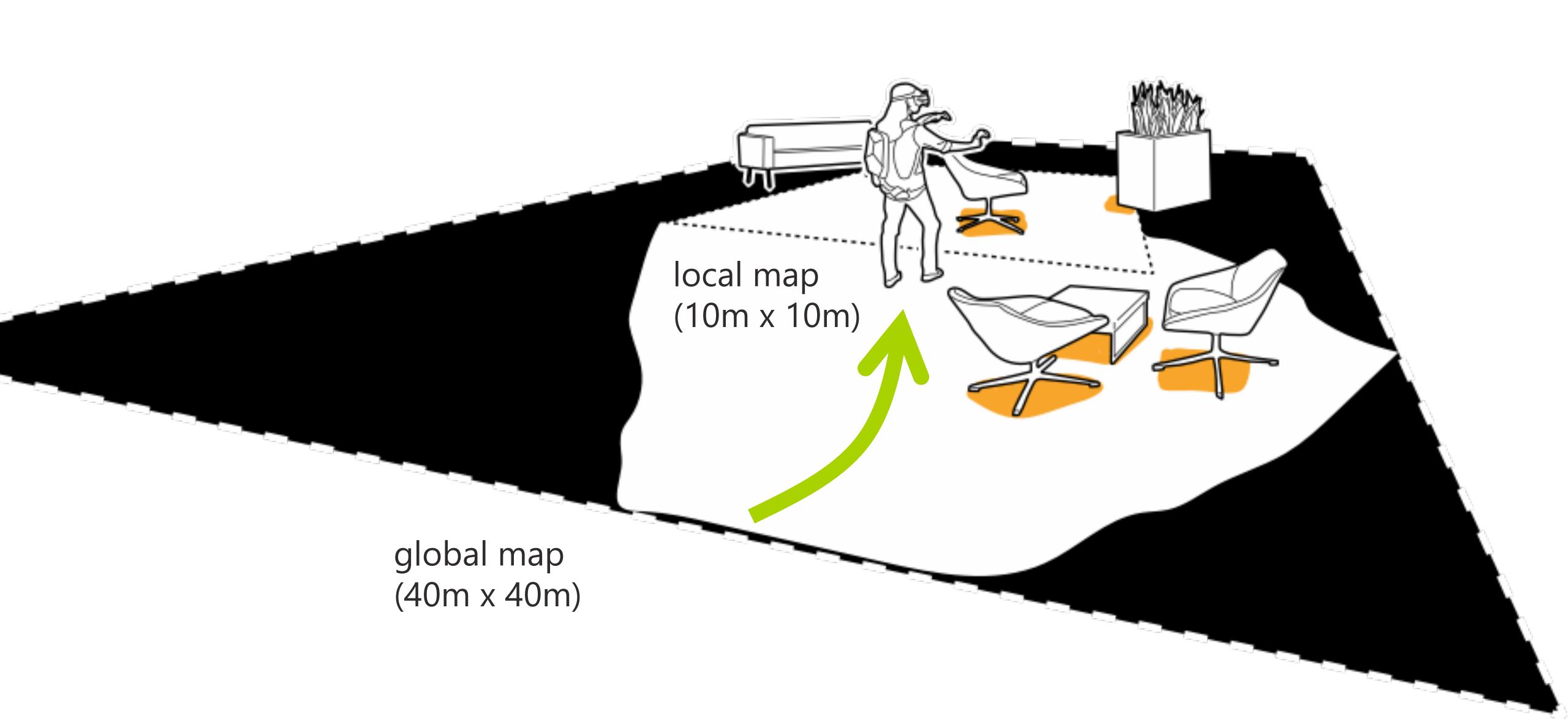




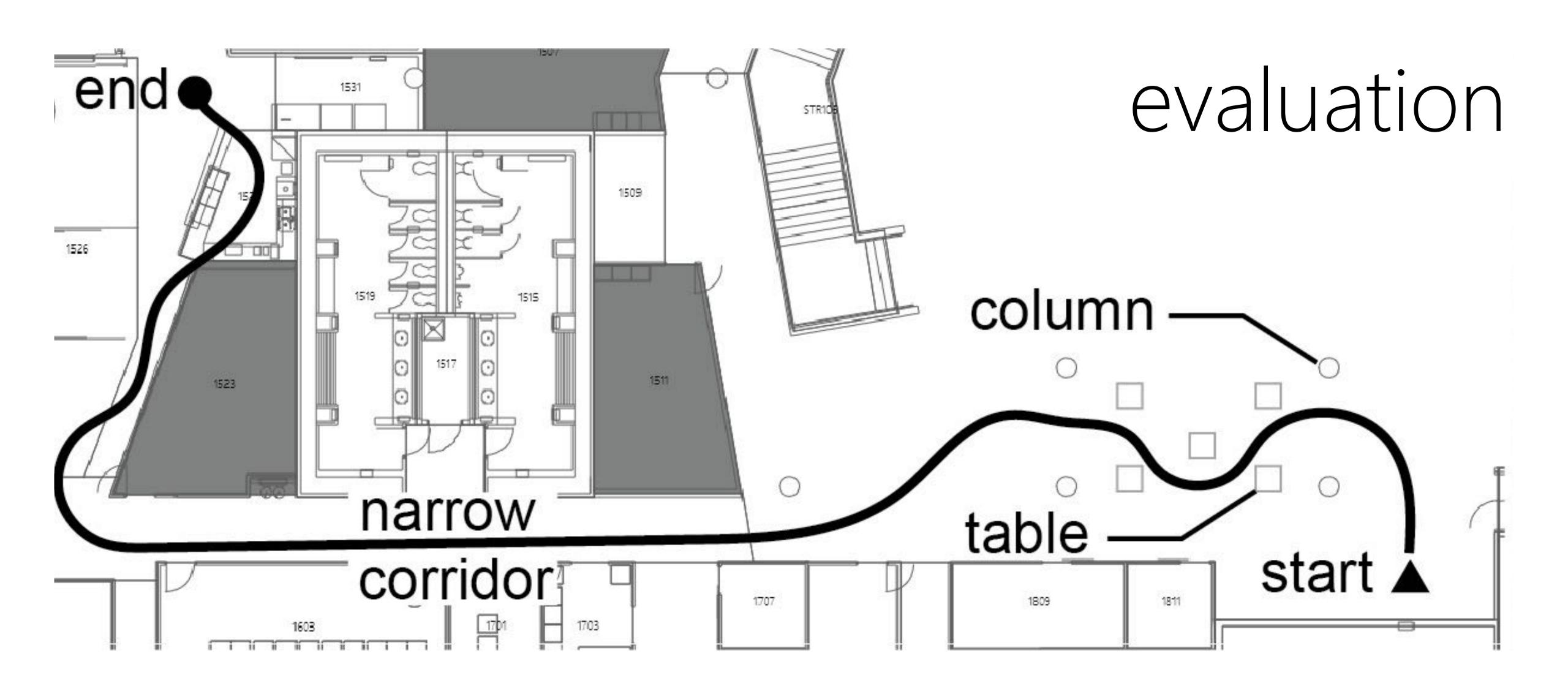
top view projection (height map)

thresholding and labeling (obstacles, floor, and unknown)



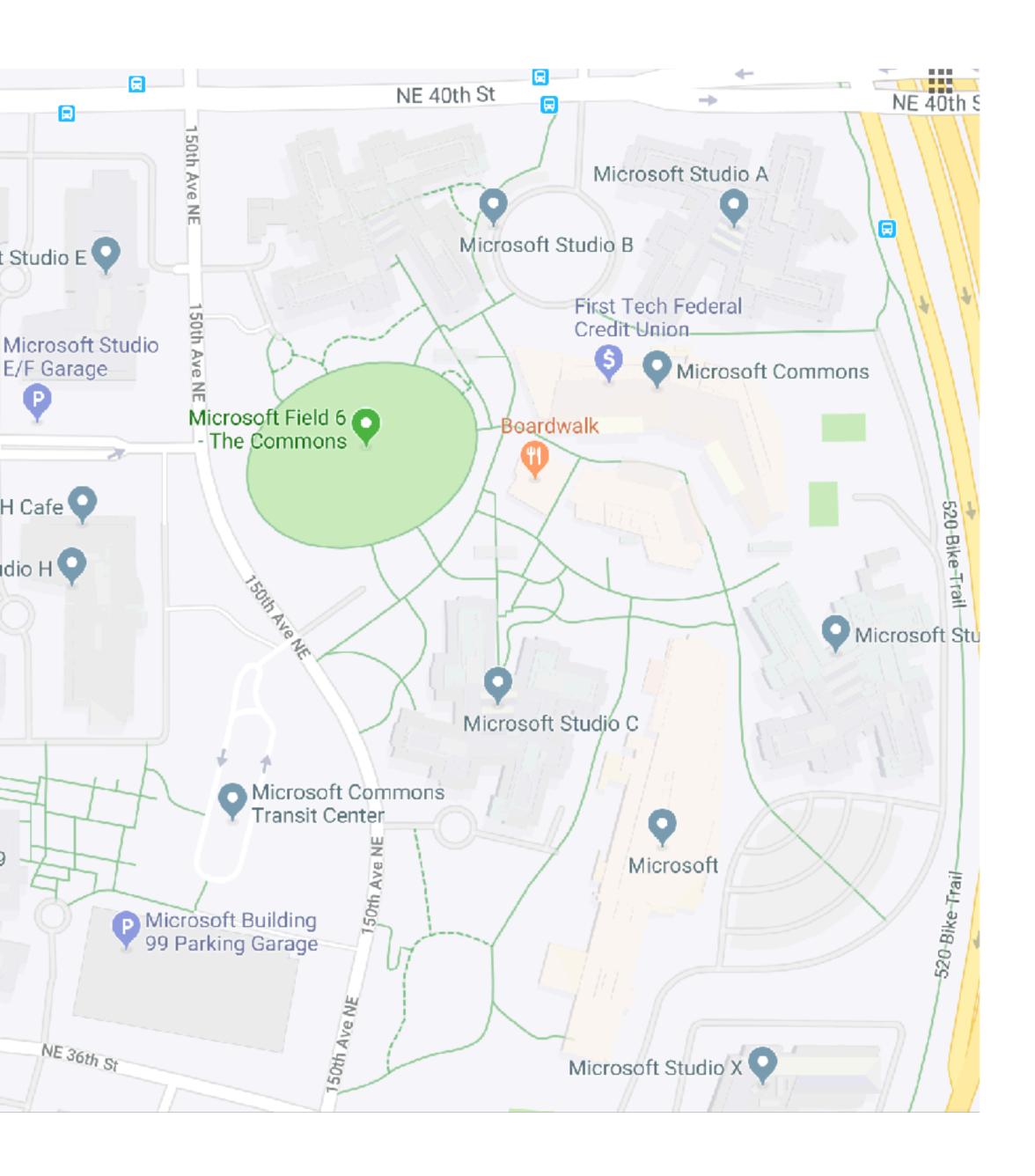






| desktop-scale | living-room scale     | garage-scale        | building                   | city |
|---------------|-----------------------|---------------------|----------------------------|------|
| small         | medium                | large               |                            | huge |
|               | controlled space, but | t limited dimension | unlimited sparbut uncontro |      |

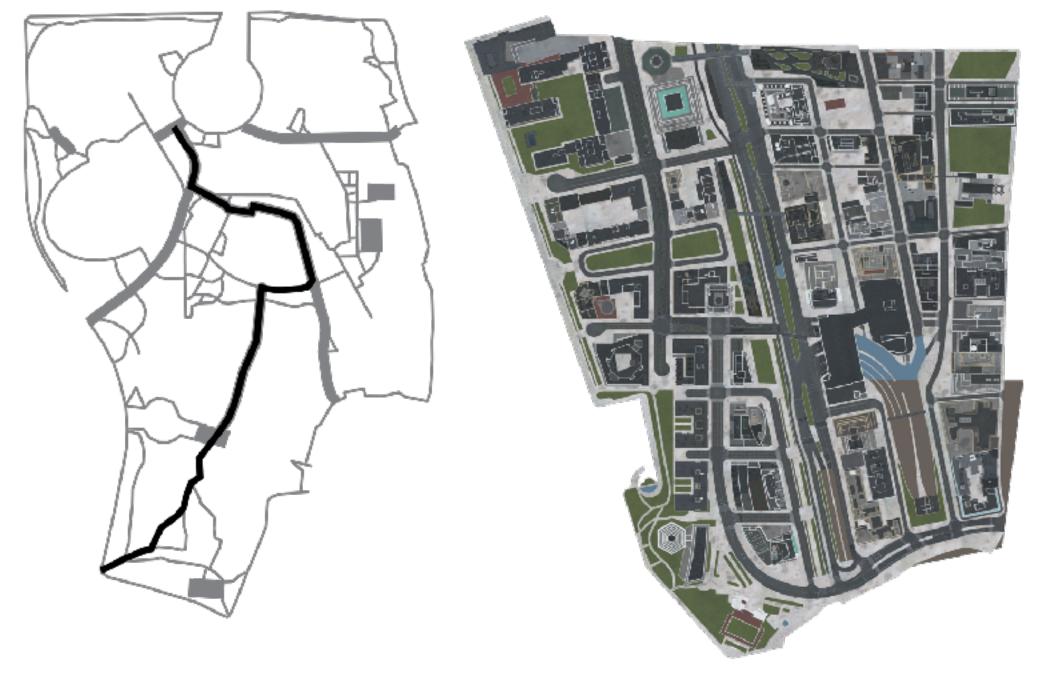




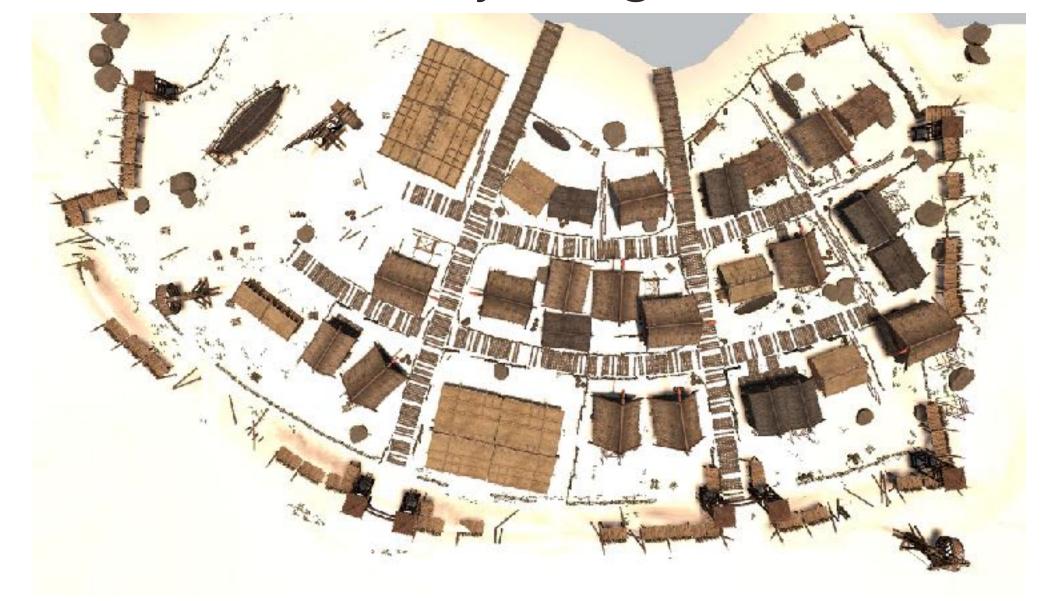
- 1) user selects a destination in the real world
- 2) route a walkable path

#### Microsoft campus

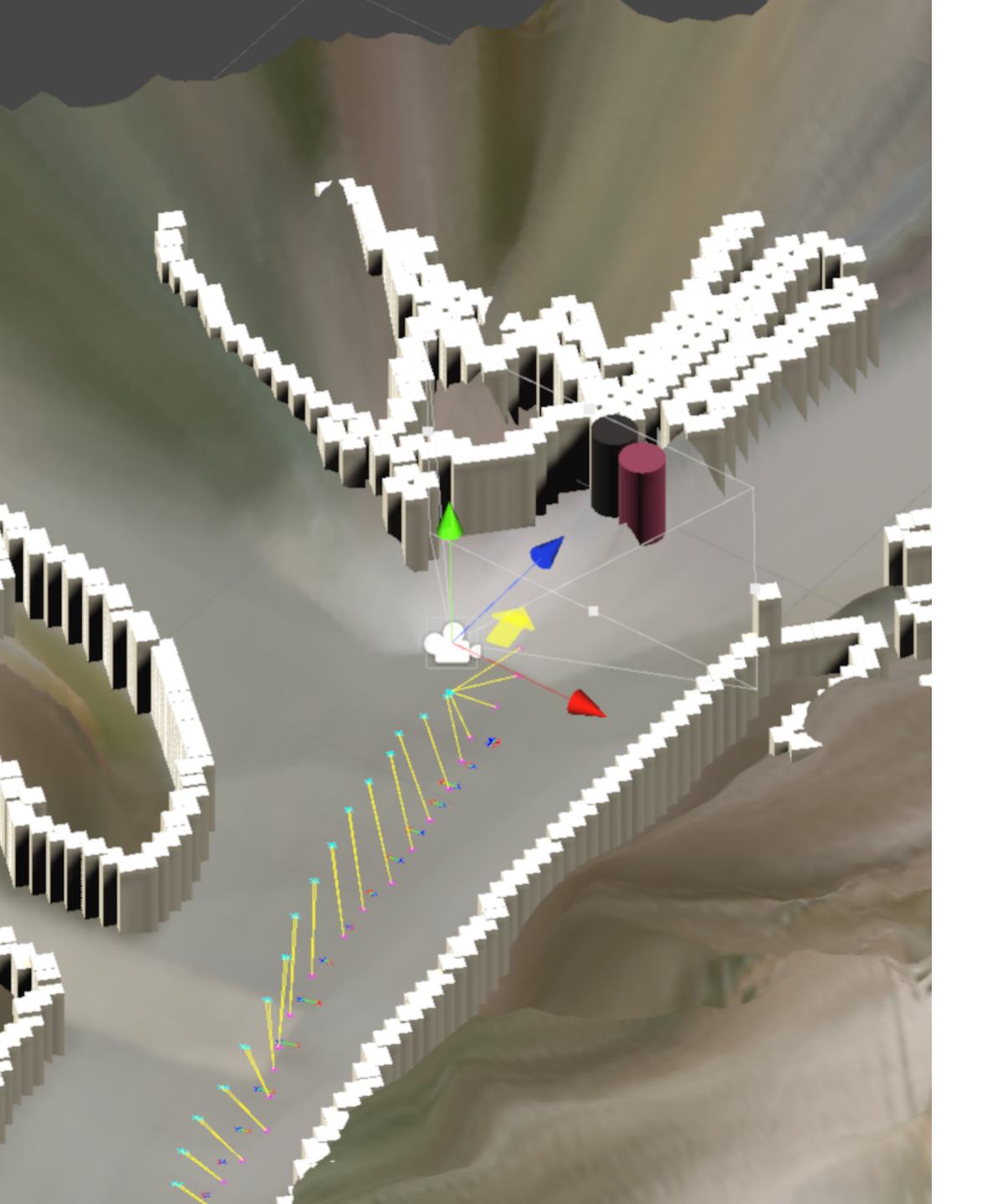
#### Manhattan



Unity Village

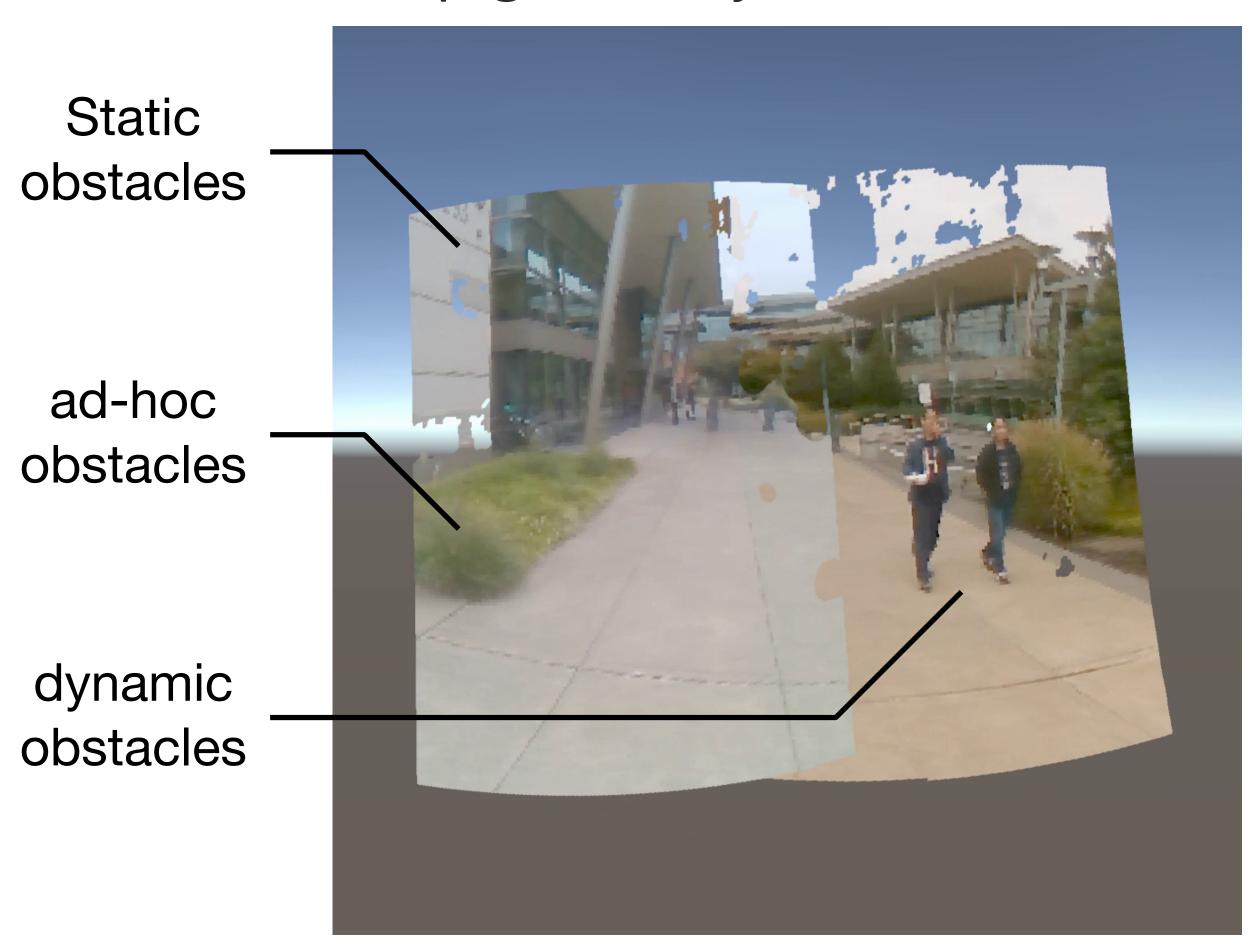


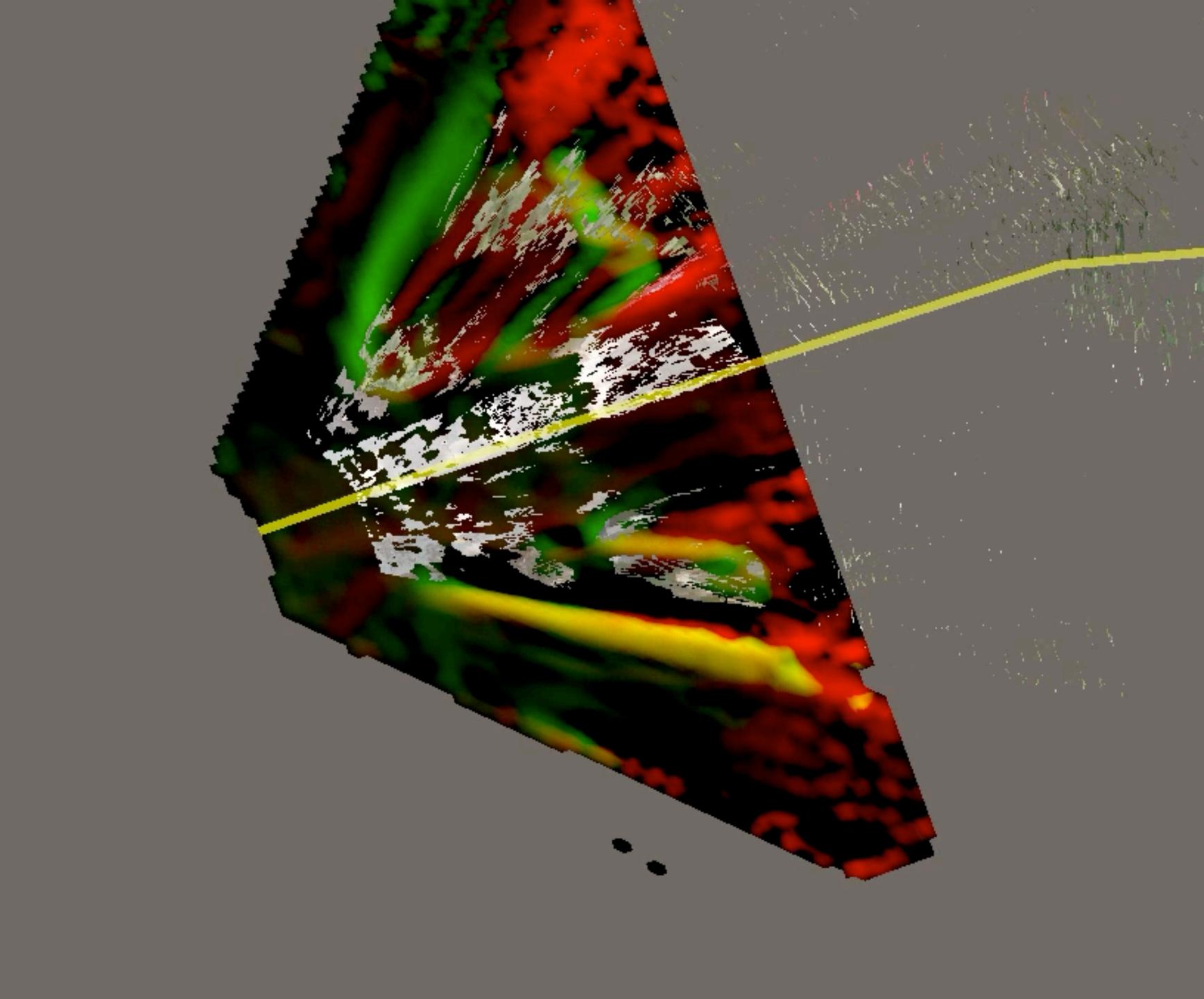
- 1) user selects a destination in the real world
- 2) route a walkable path
- 3) map a route in a virtual world



- 1) user selects a destination in the real world
- 2) route a walkable path
- 3) map a route in a virtual world
- 4) navigate through VR and prevent collisions

#### map geometry + RGBD sensor









| desktop-scale | living-room scale     | garage-scale        | building        | city |
|---------------|-----------------------|---------------------|-----------------|------|
| small         | medium                | large               |                 | huge |
|               | controlled space, but | t limited dimension | unlimited spar- |      |

