

Microsoft Research
Faculty
Summit
2016

This session – The BBC Microbit

- Thomas Ball
 - MSR

The micro:bit – overview

- Joseph Finney
 - Lancaster Univ.

The micro:bit runtime – inside and out

- Benjamin Shapiro
 - Univ. of Colorado

The micro:bit and CS education





The micro:bit – Overview

Tom Ball
Microsoft Research







BBC

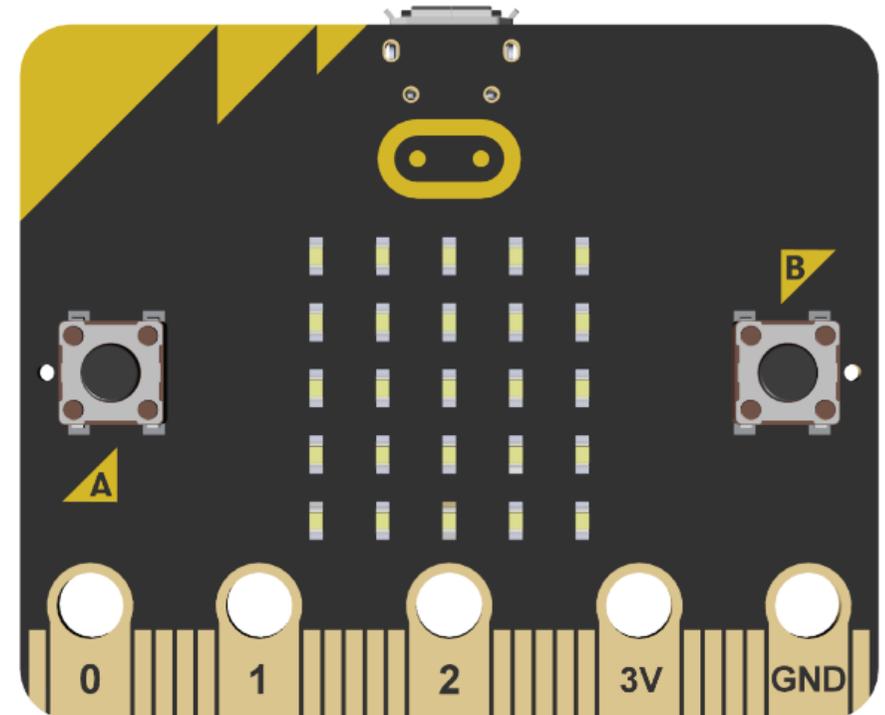


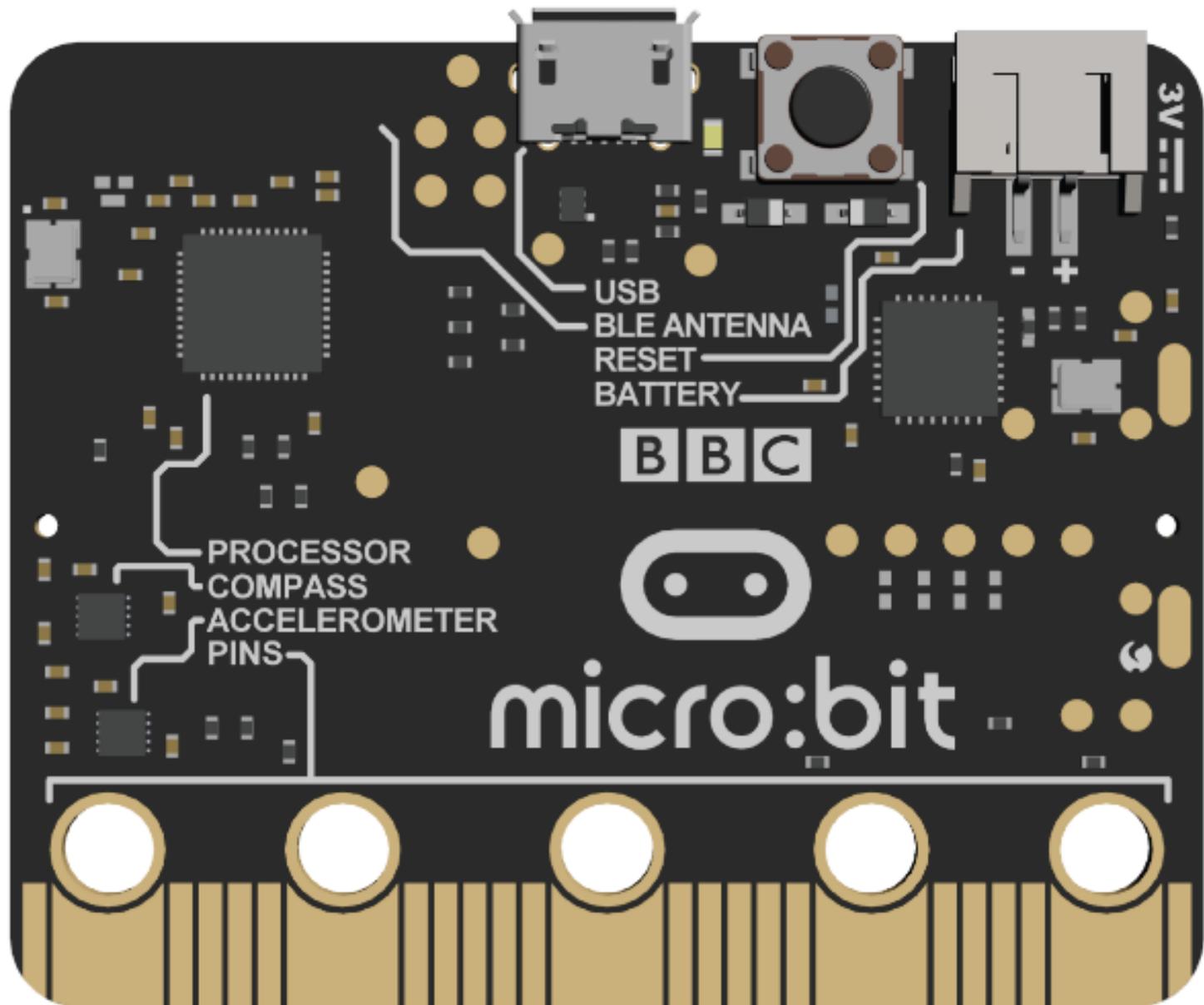
micro:bit

BBC micro:bit

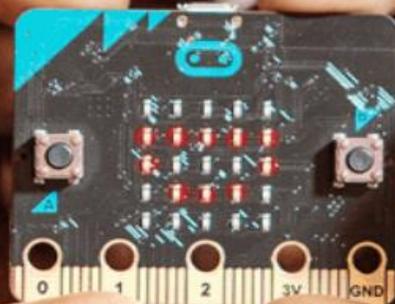
- Friendly hardware
- Friendly software
- Learning/training materials

- 1,000,000 devices seeded into UK this school year





GET CREATIVE, GET CONNECTED,
GET CODING.



Create Code

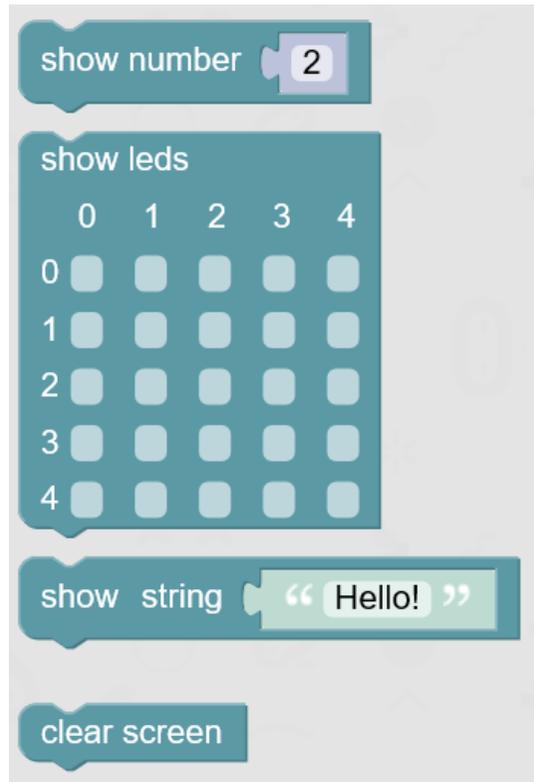
Watch Video

Discover **Everything**



Feature Rich

Display



show number 2

show leds

	0	1	2	3	4
0	<input type="checkbox"/>				
1	<input type="checkbox"/>				
2	<input type="checkbox"/>				
3	<input type="checkbox"/>				
4	<input type="checkbox"/>				

show string "Hello!"

clear screen

Sensors



button A is pressed

compass heading (°)

temperature (°C)

acceleration (mg) x

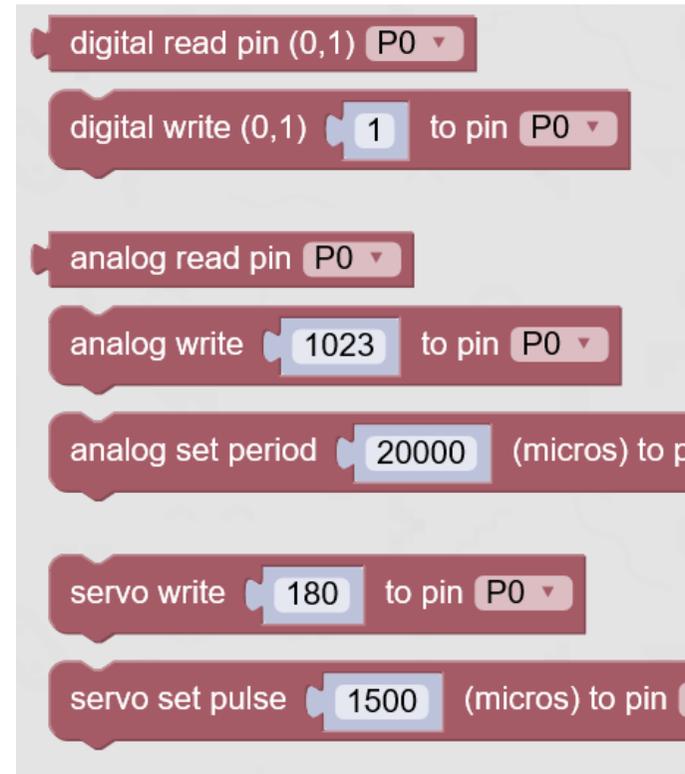
light level

rotation (°) pitch

magnetic force (microT) x

running time (ms)

I/O Pins



digital read pin (0,1) P0

digital write (0,1) 1 to pin P0

analog read pin P0

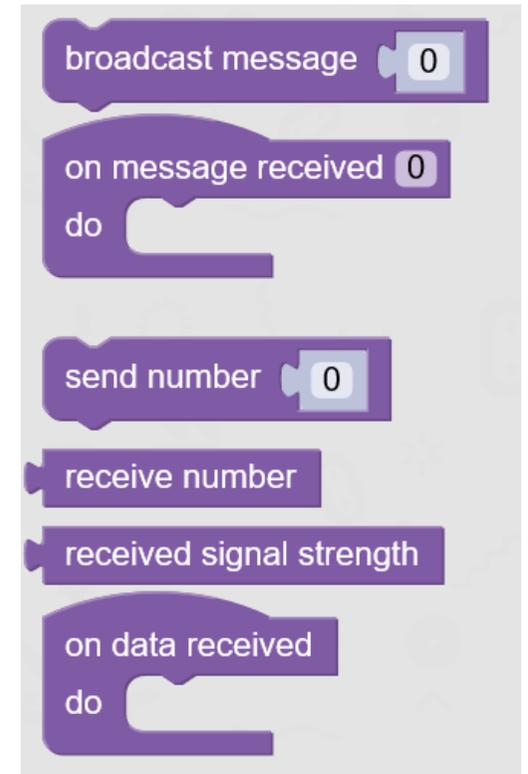
analog write 1023 to pin P0

analog set period 20000 (micros) to pin

servo write 180 to pin P0

servo set pulse 1500 (micros) to pin P

Radio



broadcast message 0

on message received 0

do

send number 0

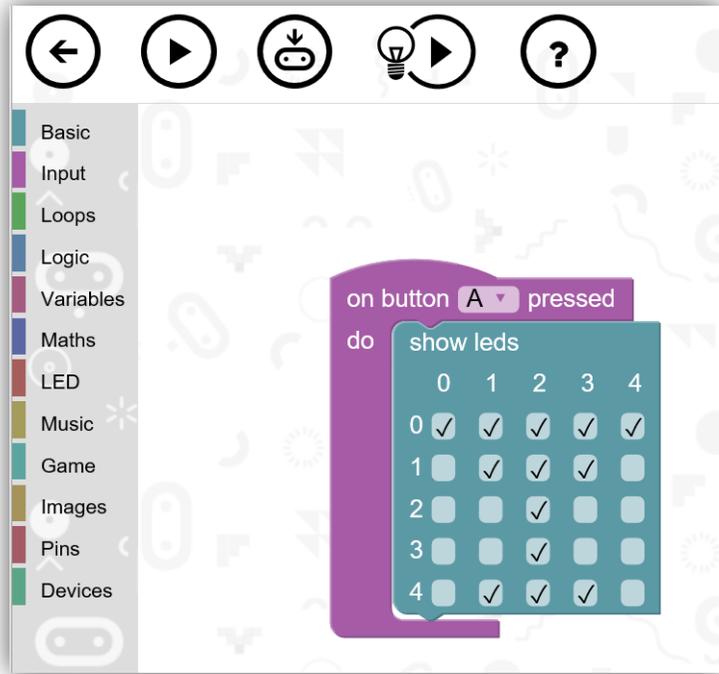
receive number

received signal strength

on data received

do

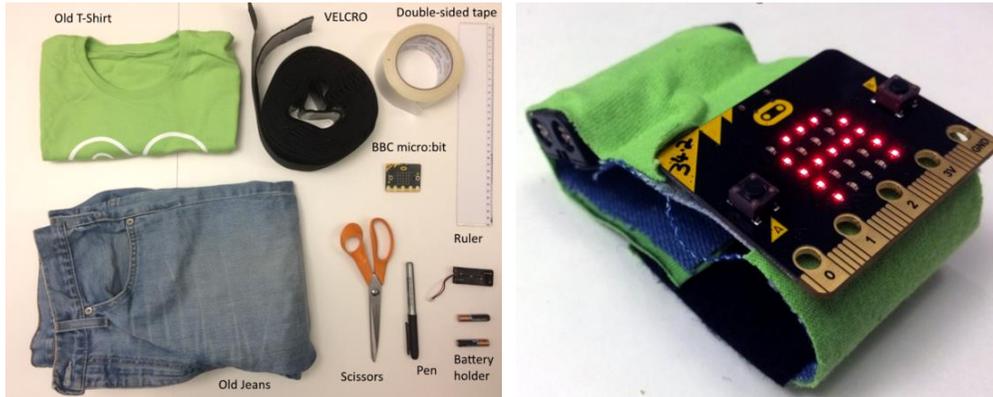
Simple to Code, Anywhere



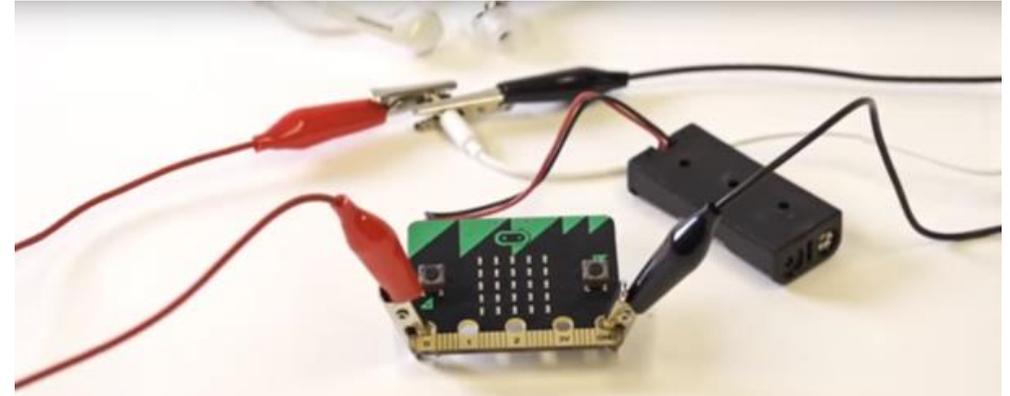
Lessons



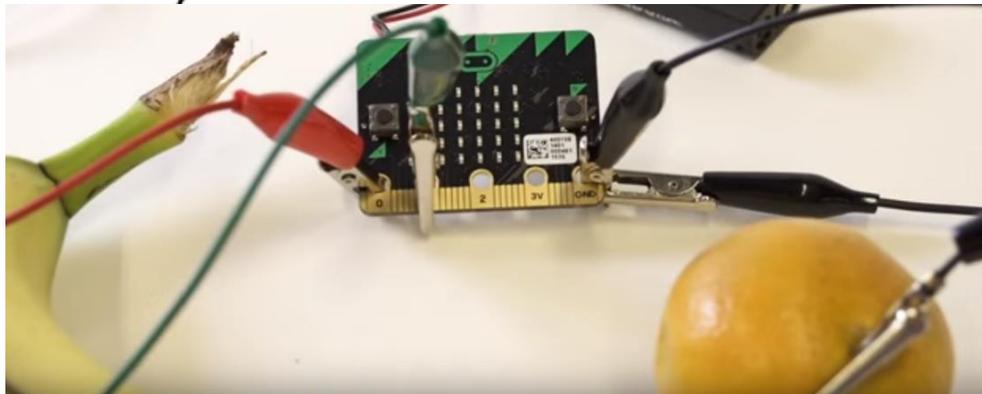
[Make your own watch](#)



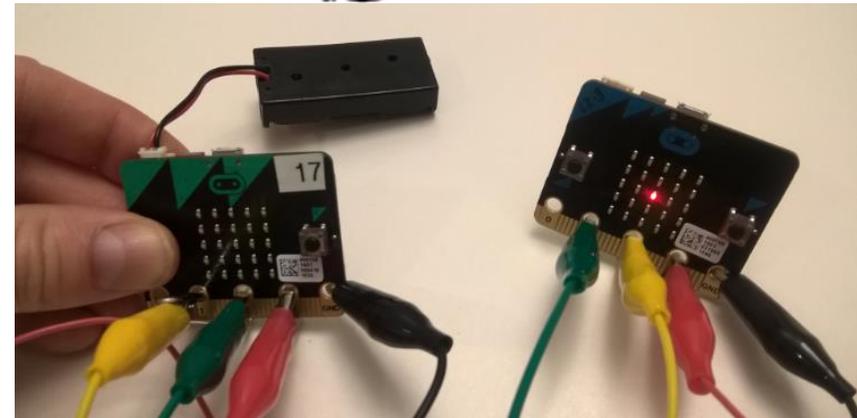
[Hack your headphones](#)



[Banana keyboard](#)



[Telegraph](#)



Core Technology Partnership



- edit/run/simulate/compile
- web site, services, lessons
- hdw design

PL



- C++ micro:bit runtime

OS

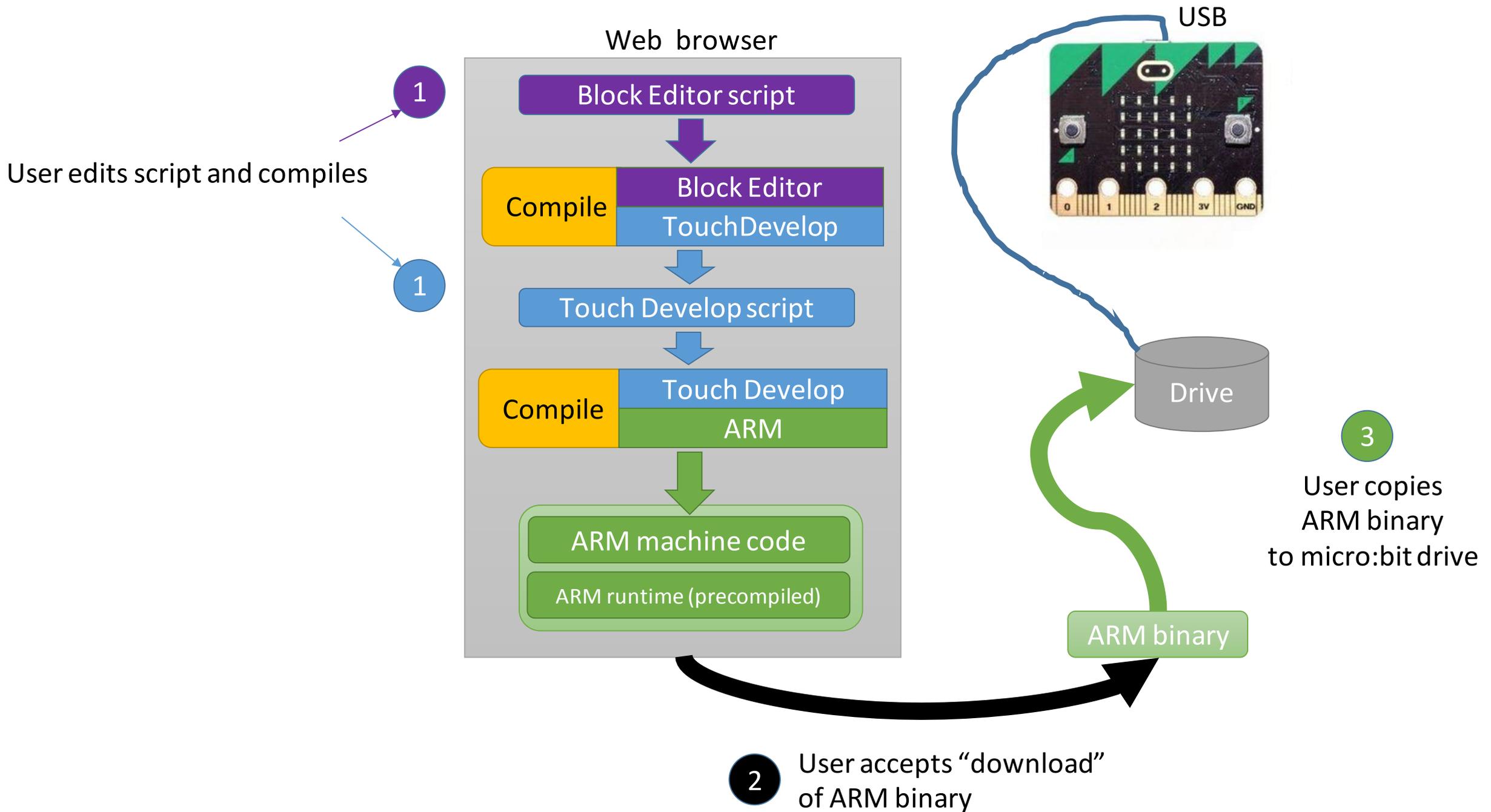


- design, mbed platform, SDK

HDW



- design, manufacture, package





Fax number:
Room Rate:
Remarks
ITEM18936588
TAX EXCLUDED

0 ORS

1

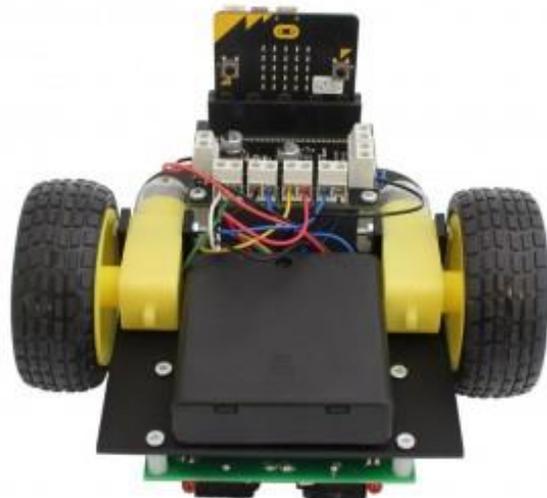
contents, priced at
(bit not included)

2

board, priced between

3

or breakout board,
2 and £3



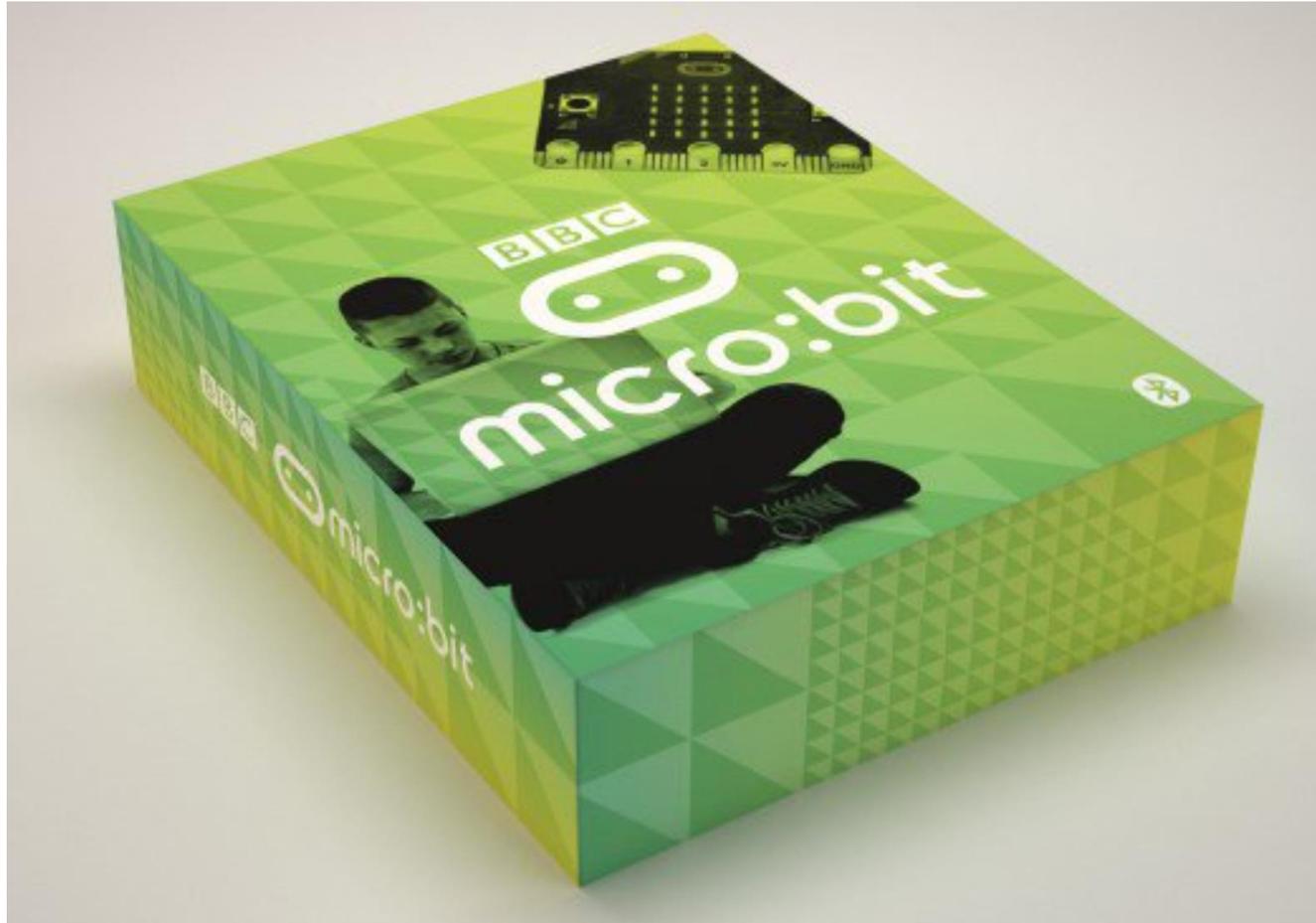


170
Members

England

What's Next?

Commercial availability: UK/EU first...

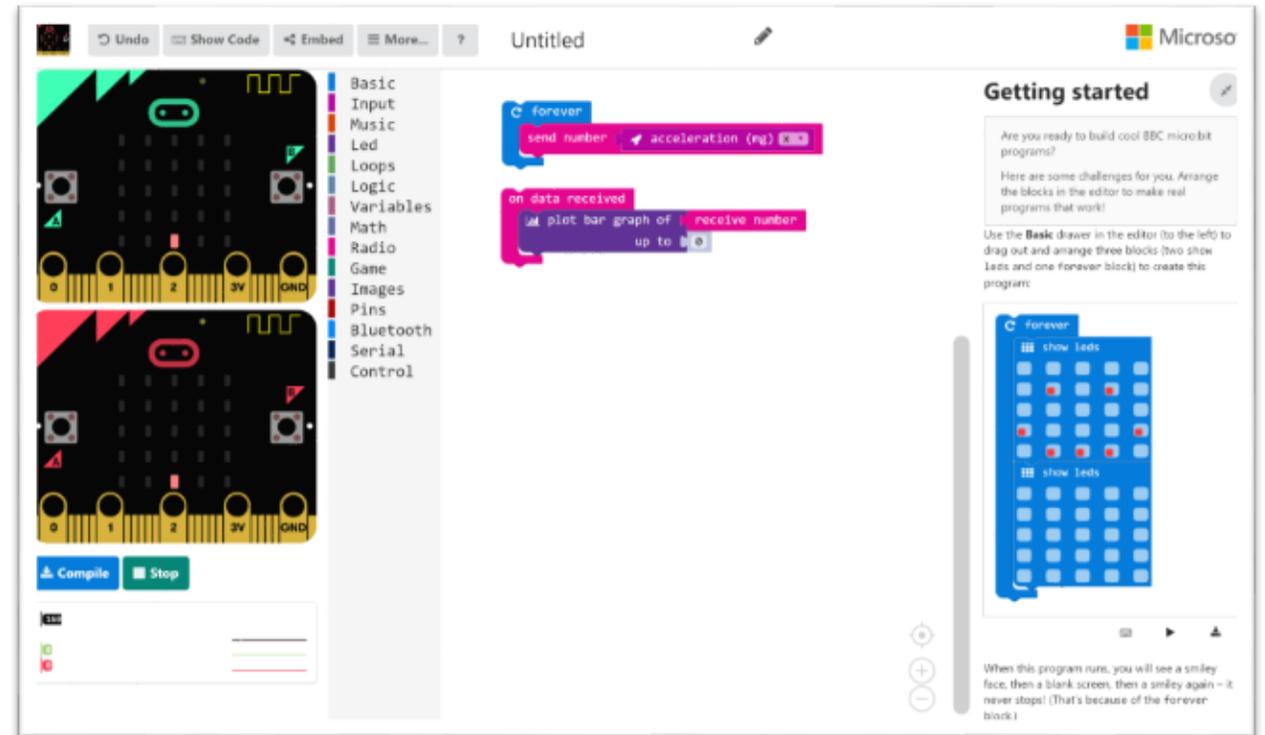


<http://uk.farnell.com/bbc-microbit>



www.codethemicrobit.com

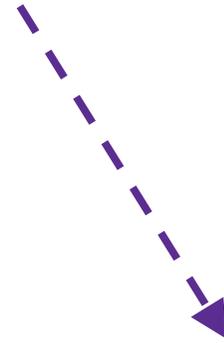
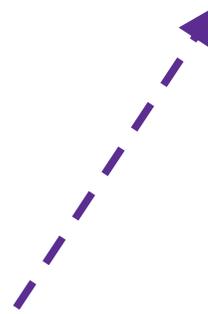
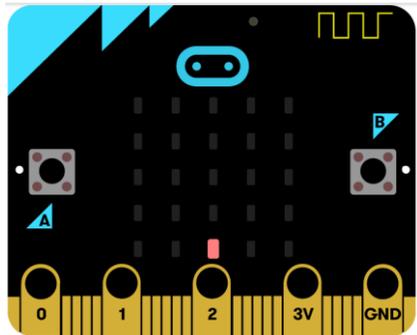
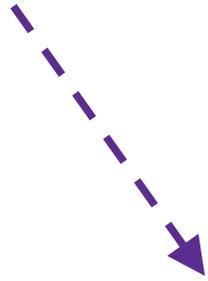
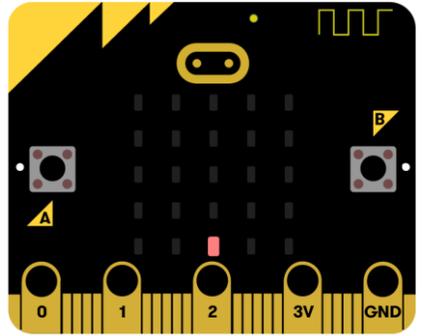
- New Microsoft web site
- Blocks \leftrightarrow JavaScript
- Streaming data to Azure
- Architected for extensibility



<https://codethemicrobit.com/tfllpvcrh>



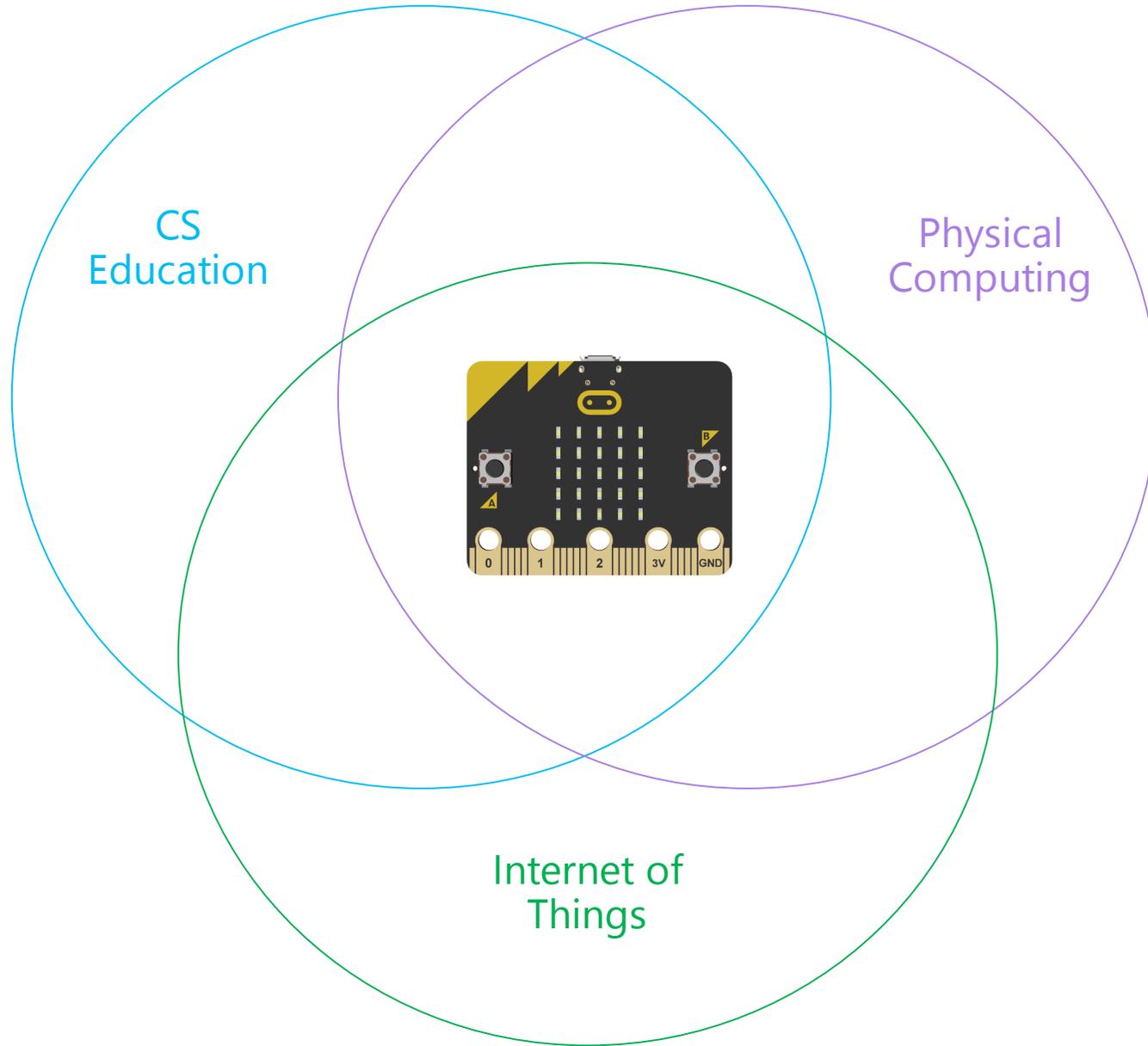
Bluetooth -> Gateway -> Azure -> Excel



Microsoft Programming Experience Toolkit

- Support new generation of microcontroller-based devices
- A simple experience combining
 - Programming progression
 - Networking of devices
 - Data analysis
- Open source
 - <http://github.com/microsoft/pxt>
 - <http://github.com/microsoft/pxt-microbit>
 - <http://github.com/microsoft/pxt-arduino>





CS
Education

Physical
Computing

Internet of
Things



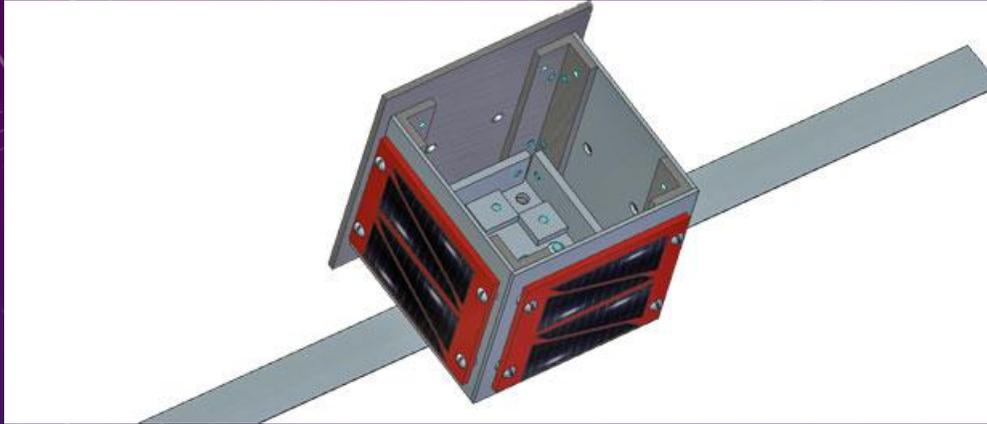
THE SATELLITE INVENTORS KIT FOR THE BBC MICRO:BIT

INSPIRING THE NEXT GENERATION OF SCIENTISTS AND ENGINEERS

ELENA BRANET, PAUL FOSTER

MICROSOFT UK, WITH THE SPACE APPLICATION CATAPULT

Nano
Satellites



CATAPULT
Satellite Applications



The Catapult PocketQube Satellite Kit

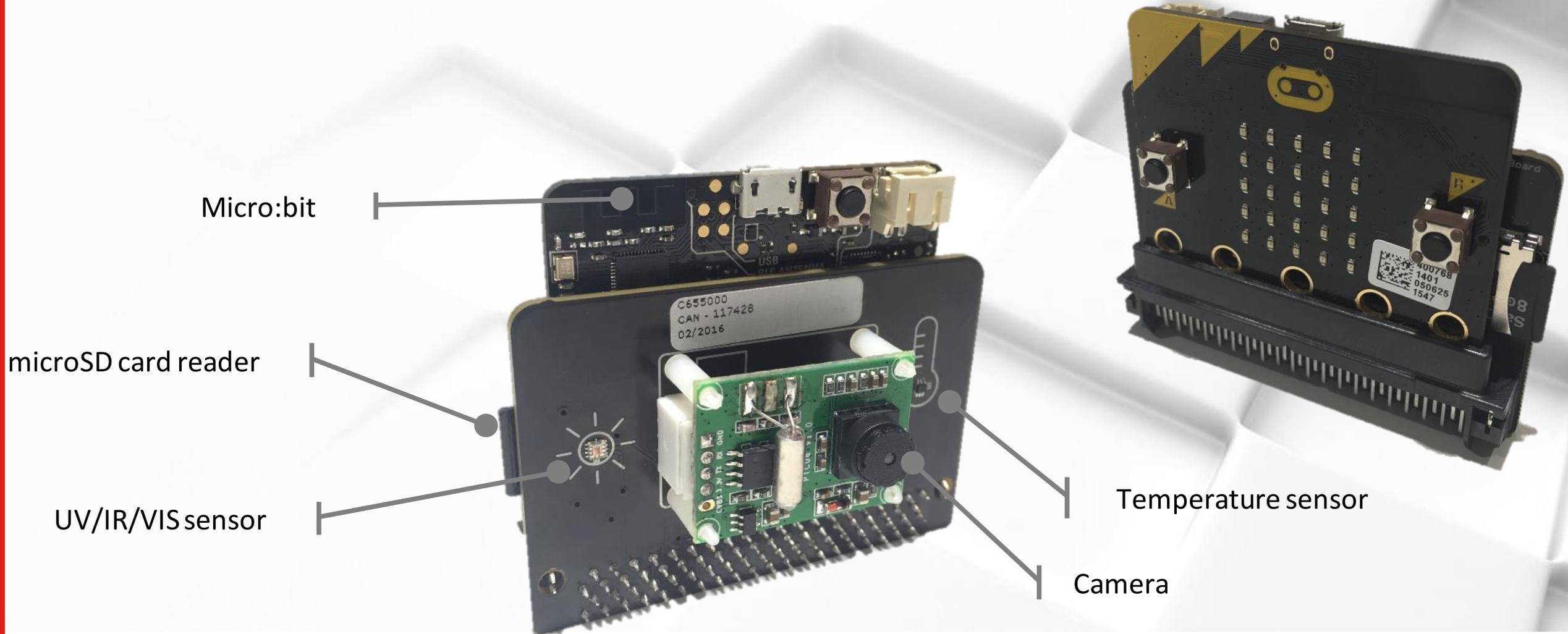
- A complete satellite in a 5 cm cube
- A fully functional, self-contained, remotely operated platform

Education
Training
Experiment
Instrument
Mission design



CATAPULT OPEN

The Micro:bit Satellite Inventors Kit



Concepts

- **Coding**

- Real world problems and physical systems
- Developing creativity

- **Design and technology**

- Iterative design and building

- **Biology**

- Biological ecosystems
- Plant reproduction and the environment
- Photosynthetic processes
- Photosynthesis and the atmosphere
- Adaptation of leaves for photosynthesis

- **Chemistry**

- The carbon cycle

- **Physics**

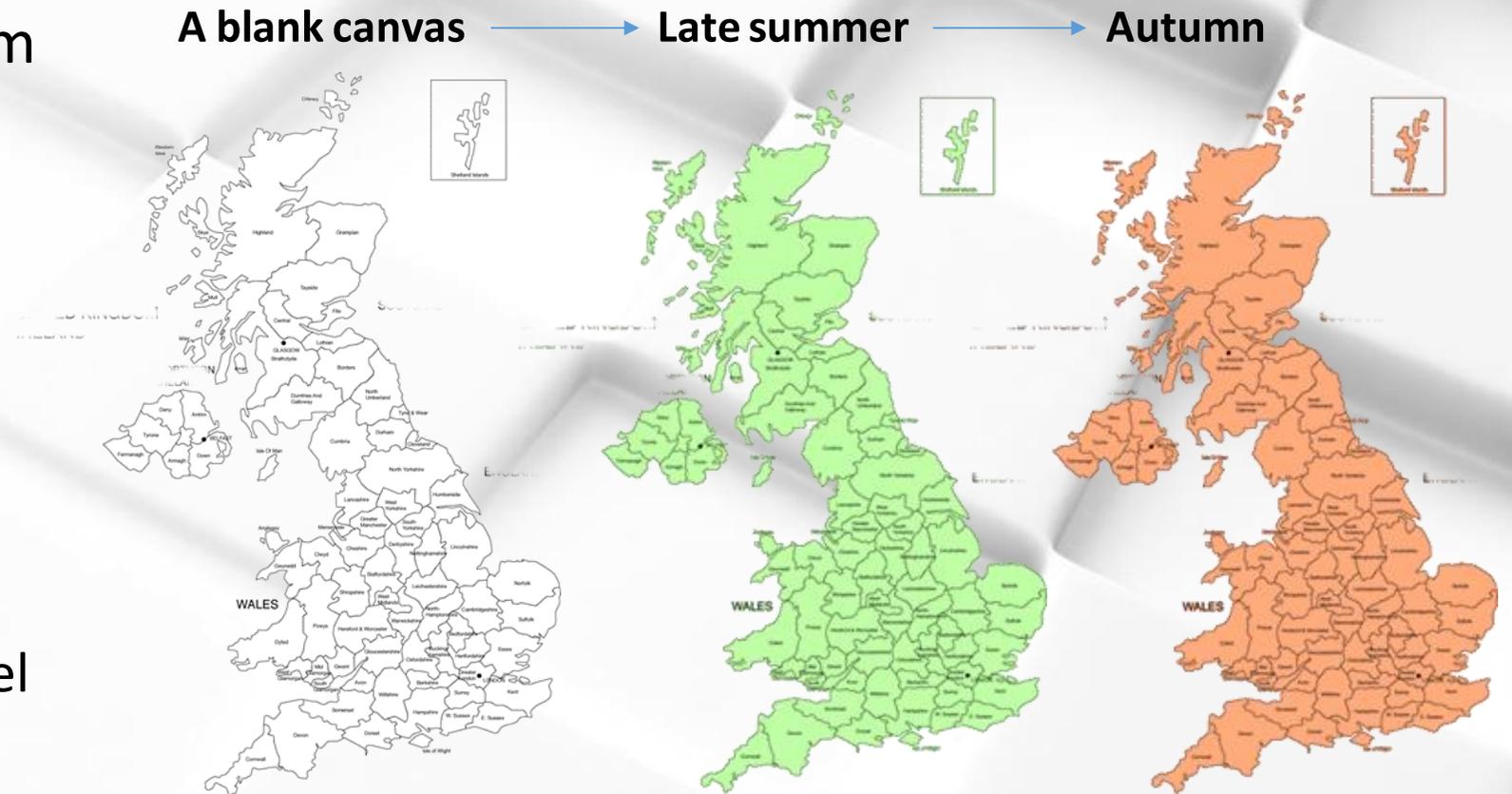
- Radiation, convection and conduction
- Gravity as a force
- Waves
- Electricity
- Magnetism
- Forces
- The Sun
- The seasons

- **Geography**

- Interpreting geographical info

A national crowd-sourced data experiment

- Using micro:bits and satellite inventor's kits in the classroom
- Minimum of one per county
- Crowd-source monitoring the change in seasons
 - Collect an image
 - Process the image data
 - Upload the data point to the cloud
 - Geotag data to locate the pixel
 - Play back to demonstrate the change in season



Call to Action

- Educators to incorporate micro:bit into courses
- Research partners to extend the PXT platform
- Hardware partners to extend to new devices

- See me during Faculty Summit to get a micro:bit

- Follow-up via e-mail to tball@microsoft.com

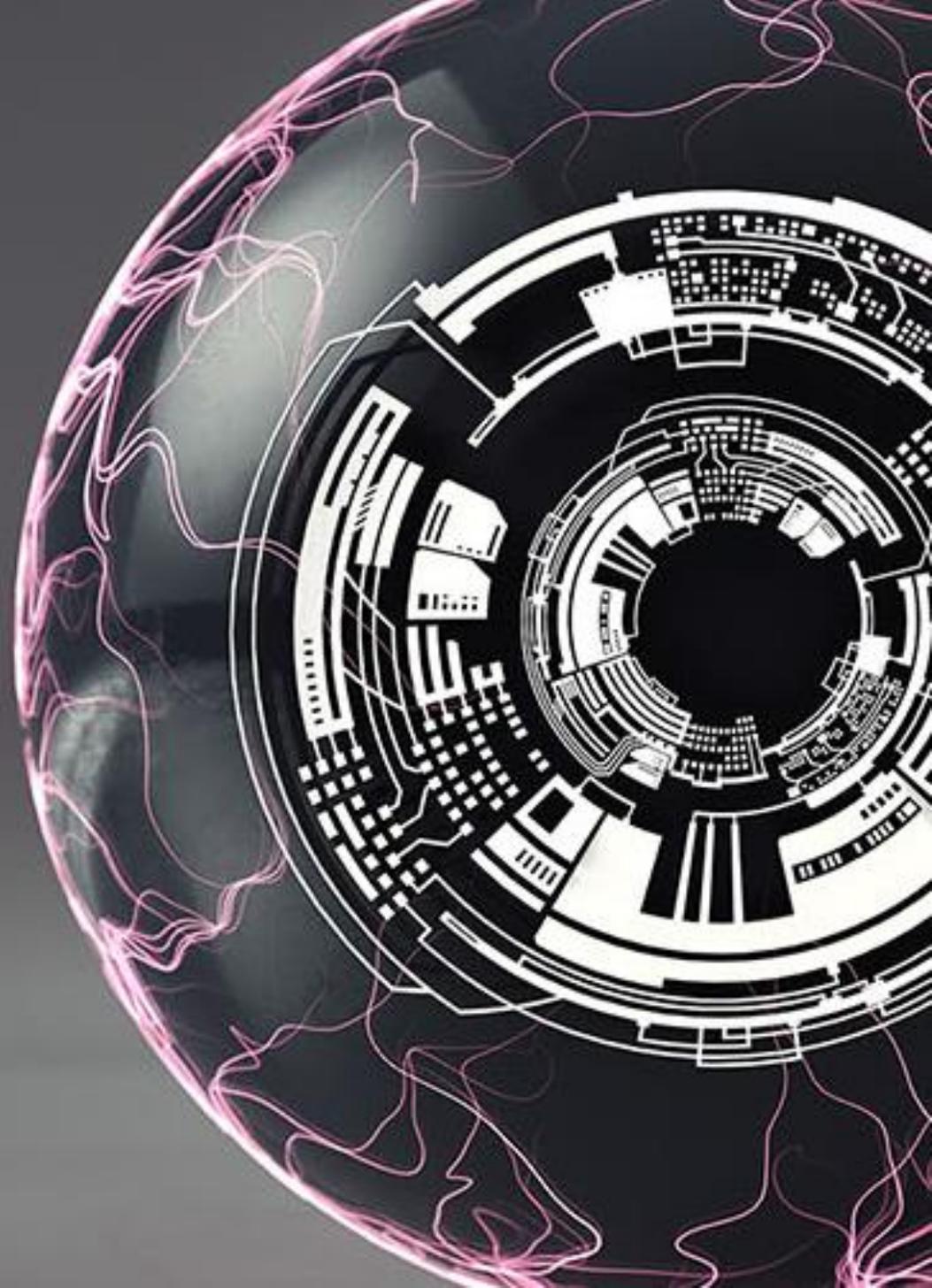




The micro:bit runtime Inside and Out

Joe Finney
Lancaster University, UK

joe@comp.lancs.ac.uk





- 25 LED matrix screen
- Light sensor
- User definable buttons

- 17 Digital input/output
- 6 Analog input
- 3 PWM output
- 3 Touch sensitive
- I2C, SPI, UART



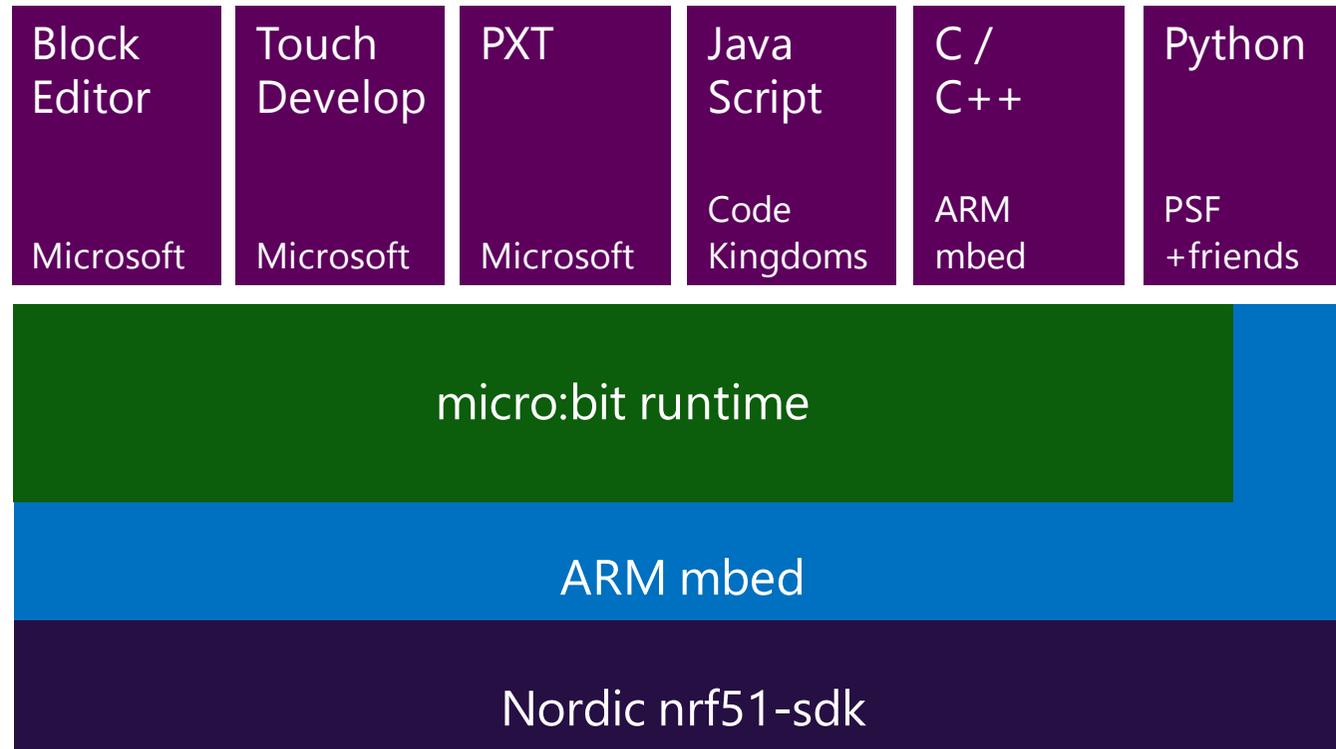


- 16MHz ARM Cortex M0
- 16KB RAM, 256K FLASH
- USB Storage/Serial/Debug
- 3 axis accelerometer
- 3 axis magnetometer
- Temperature sensor
- Bluetooth Low Energy



micro:bit runtime architecture

The micro:bit community encourages many languages...

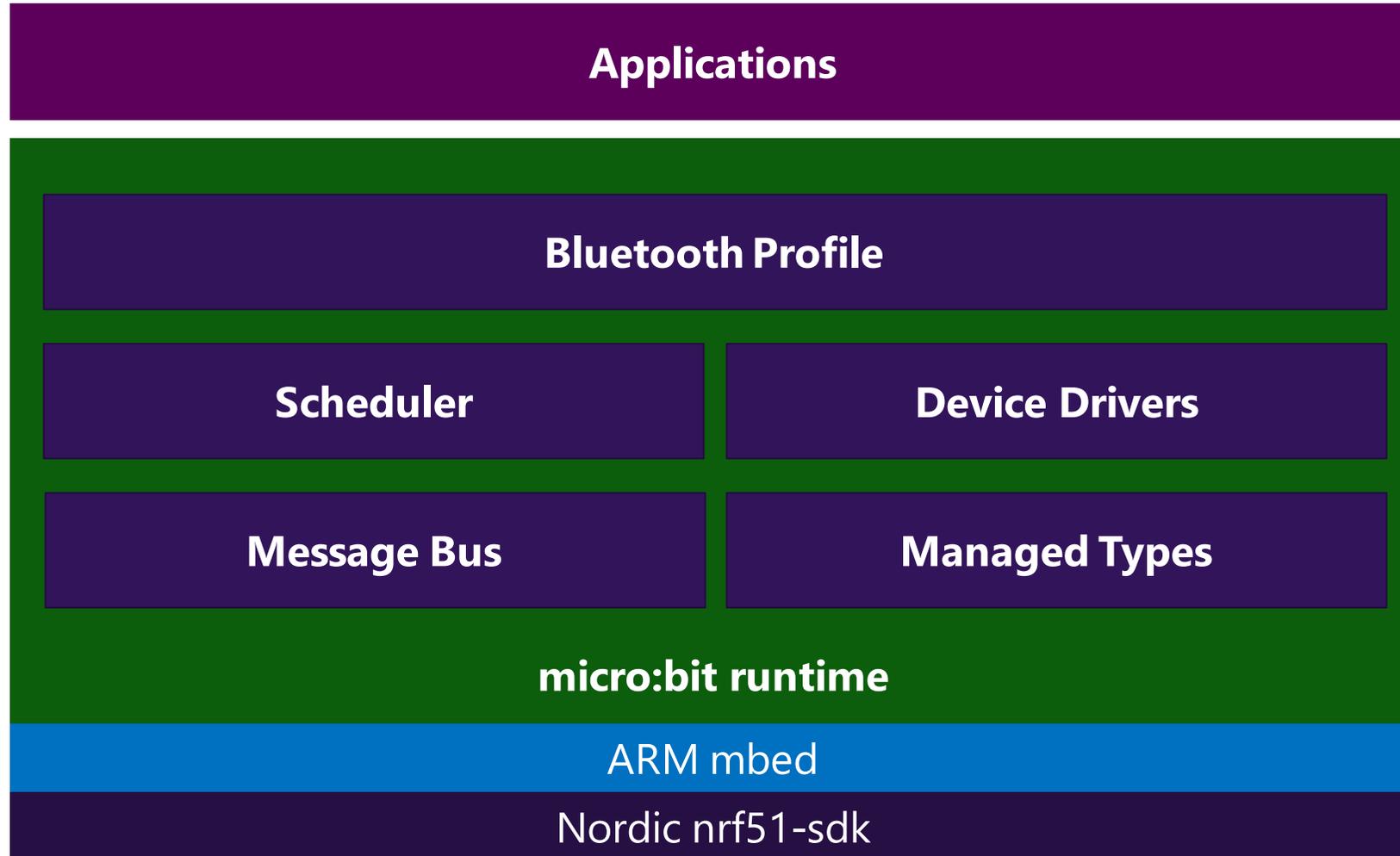


Introducing the micro:bit runtime

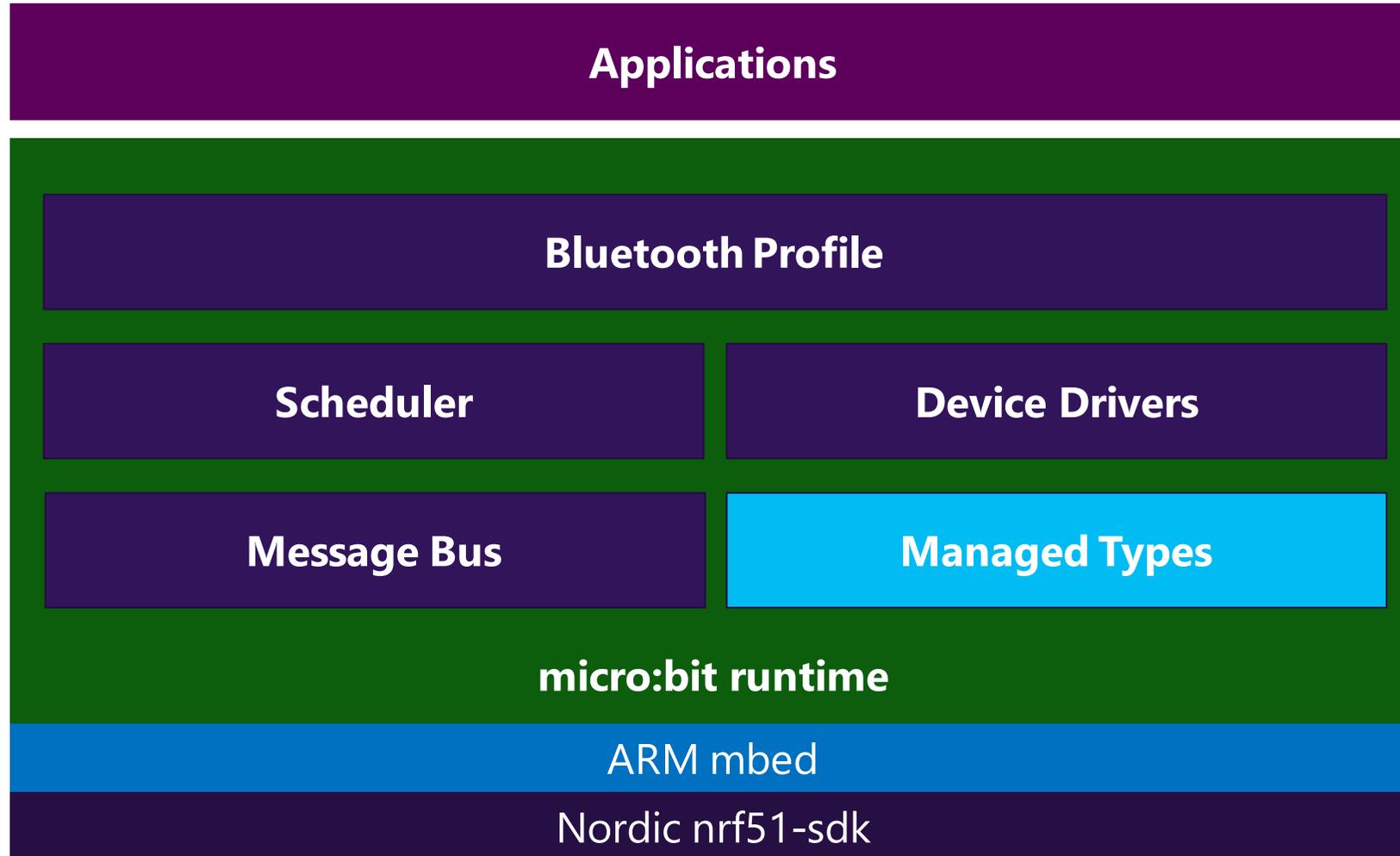
- Provides a Device Abstraction Layer for the micro:bit...
 - Open source C/C++ component based API
 - Designed with many requirements in mind:
 - High level language features (concurrency, eventing models and memory safety)
 - Native C/C++ friendliness
 - RAM efficiency
 - Power efficiency



micro:bit runtime architecture



micro:bit runtime architecture



Managed Types

- C is a great language for building software that works with hardware...
 - as it gives a lot of **power** to its users.
- Higher level languages are great for building applications
 - as they make it **easy, robust and simple** for the user.

Memory Management is a key distinction. e.g. take some classic C code:

```
char *s = malloc(10);  
  
strcpy(s, "hello");  
doSomething(s);
```

```
void  
doSomething(char *text)  
{  
    ...  
}
```

**who is responsible for
freeing the data?**

Managed Types

- Modern high level languages assume this is handled by their runtime - so we do!
- Commonly used data types (strings, images, packets) all have their own data type
- Uses **reference counting** to track when the data is used (simpler, but similar principle to JVM, CLR)
- Transparent to users and high level languages. Feels like a higher level language...

```
ManagedString s = "hello";  
doSomething(s);
```

```
void  
doSomething(ManagedString text)  
{  
    ...  
}
```

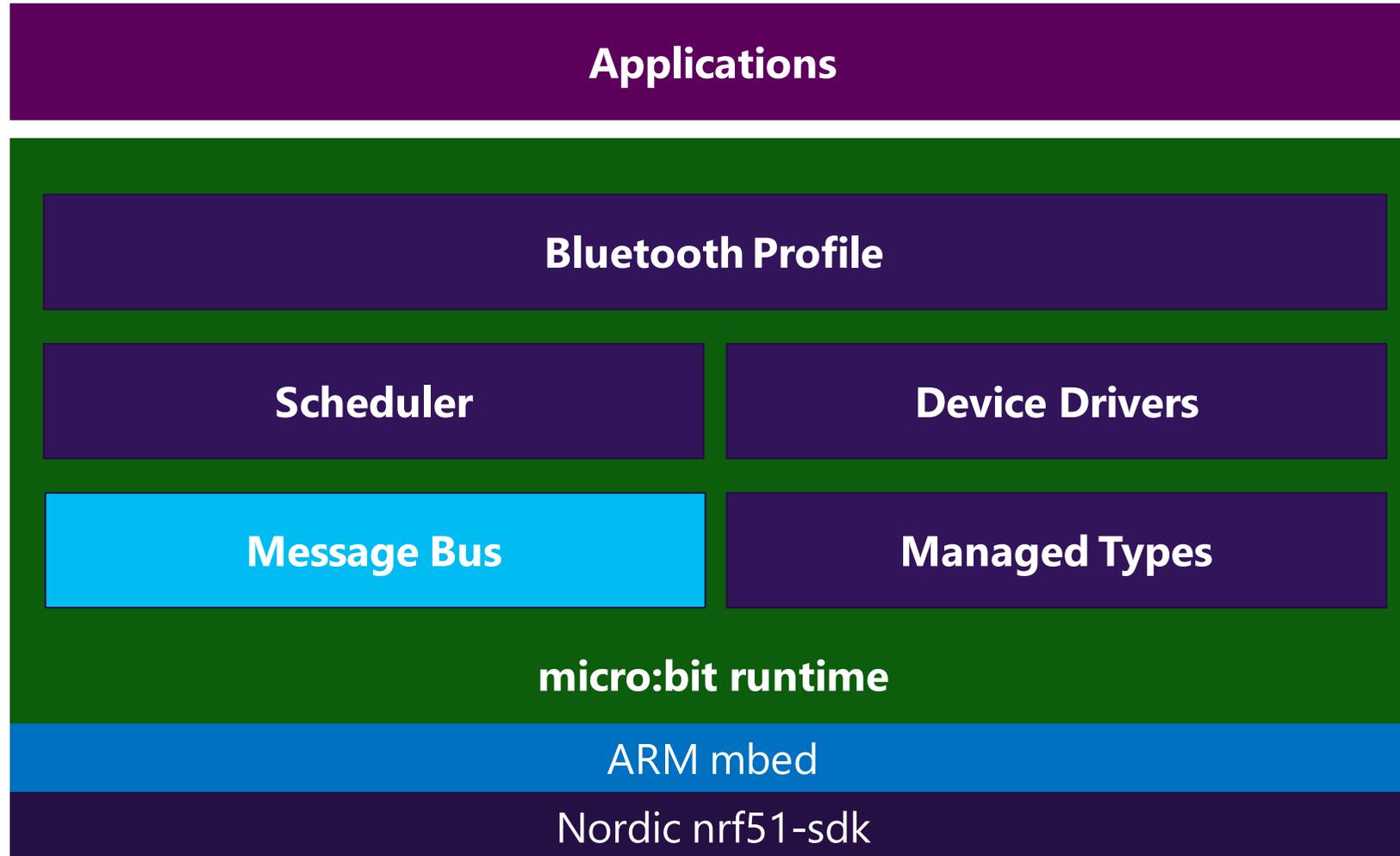
Managed Types

- Higher level languages can then more easily map onto the runtime.
- It also provides a clean, easy to use API for C/C++ users:

```
ManagedString s, t, message, answer;  
  
s = "hello";  
t = "world";  
  
message = s + " " + t;  
  
answer = "The answer is:" + 42;  
  
if (message == answer)  
    ...
```

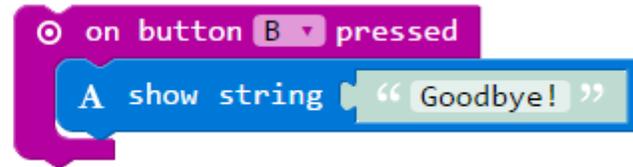


micro:bit runtime architecture



Eventing and the Message Bus

- Many languages support the concept of events.
- This is also something that kids find familiar from visual languages such as Scratch.
- And something that lends itself to embedded systems too... e.g.



Eventing and the Message Bus

- The micro:bit runtime contains a simple yet powerful extensible eventing model
- Events are themselves a very simple managed type.
- Contain two numeric values: a **source** and a **value**.
- Every component in the runtime has a unique ID – the source of an event.
- Each component can then create ANY value with that ID as a source at any time:

```
MicroBitEvent e(MICROBIT_ID_GESTURE, MICROBIT_ACCELEROMETER_EVT_SHAKE);
```

```
#define MICROBIT_ID_GESTURE 27  
#define MICROBIT_ACCELEROMETER_EVT_SHAKE 11
```



Eventing and the Message Bus

- The **MessageBus** then delivers events to any code that registers an interest.
- Functions can be either plain C functions, or C++ methods.
- Wildcard values can also be used to capture lots of events at once.
- There's also a matching **ignore** function in case you want to stop receiving events.

```
void onShake(MicroBitEvent e)
{
    // do something cool here!
}

int main()
{
    uBit.messageBus.listen(MICROBIT_ID_GESTURE, MICROBIT_ACCELEROMETER_EVT_SHAKE, onShake);
}
```



Eventing and the Message Bus

- The **MessageBus** then delivers events to any code that registers an interest.
- Functions can be either plain C functions, or C++ methods.
- Wildcard values can also be used to capture lots of events at once.
- There's also a matching **ignore** function in case you want to stop receiving events.

```
void onGesture(MicroBitEvent e)
{
    if (e.value == MICROBIT_ACCELEROMETER_EVT_SHAKE) ...
}

int main()
{
    uBit.messageBus.listen(MICROBIT_ID_GESTURE, MICROBIT_EVT_ANY, onGesture);
}
```



Eventing and the Message Bus

- The **MessageBus** then delivers events to any code that registers an interest.
- Functions can be either plain C functions, or C++ methods.
- Wildcard values can also be used to capture lots of events at once.
- There's also a matching **ignore** function in case you want to stop receiving events...

```
void onEvent(MicroBitEvent e)
{
    if (e.source == MICROBIT_ID_GESTURE) ...
}

int main()
{
    uBit.messageBus.listen(MICROBIT_ID_ANY, MICROBIT_EVT_ANY, onEvent);
}
```



Eventing and the Message Bus

- The runtime generates a range of events application can build on.
 - Users can also define their own events easily... just numbers!

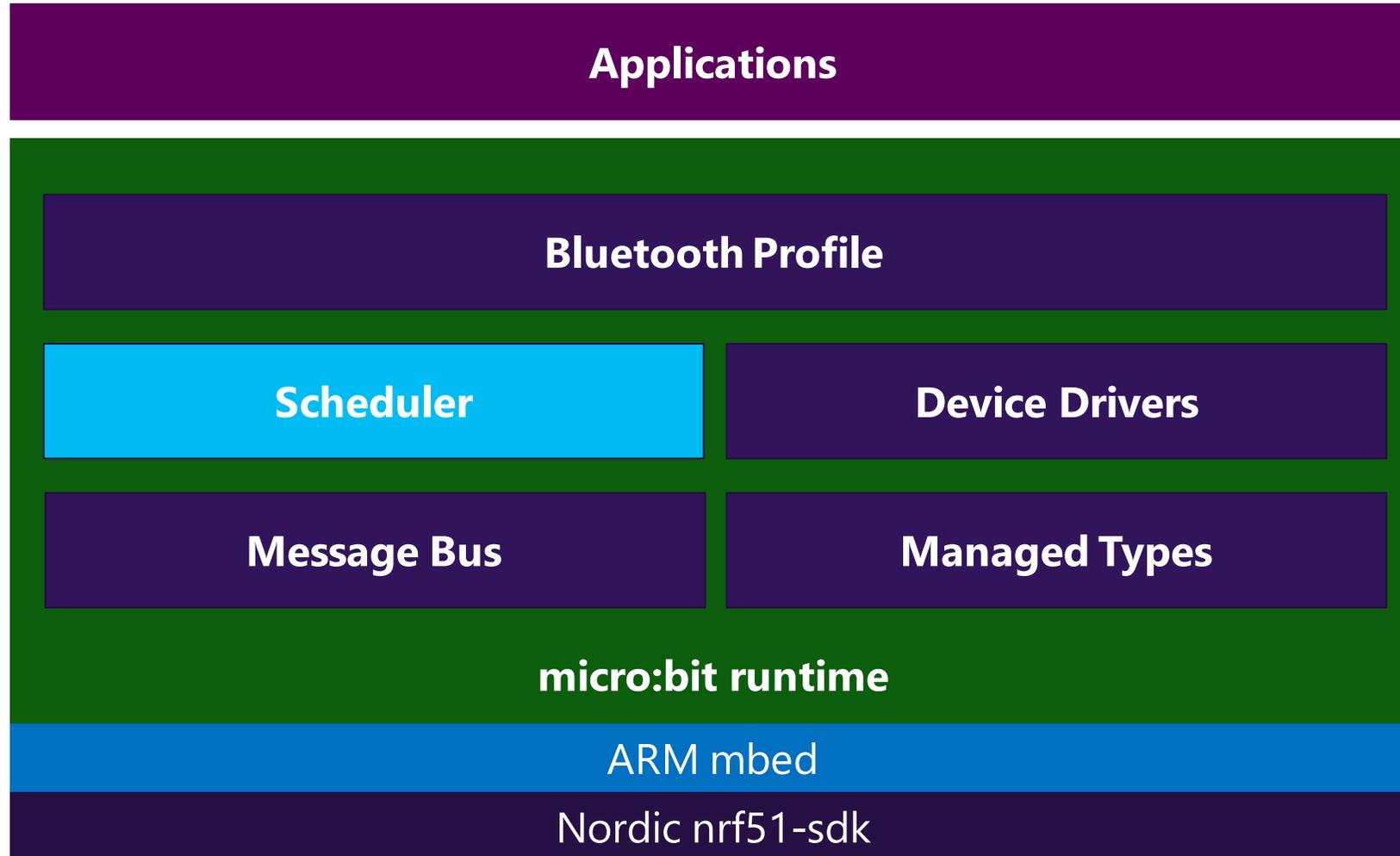
```
#define MICROBIT_ACCELEROMETER_EVT_TILT_UP 1
#define MICROBIT_ACCELEROMETER_EVT_TILT_DOWN 2
#define MICROBIT_ACCELEROMETER_EVT_TILT_LEFT 3
#define MICROBIT_ACCELEROMETER_EVT_TILT_RIGHT 4
#define MICROBIT_ACCELEROMETER_EVT_FACE_UP 5
#define MICROBIT_ACCELEROMETER_EVT_FACE_DOWN 6
#define MICROBIT_ACCELEROMETER_EVT_FREEFALL 7
#define MICROBIT_ACCELEROMETER_EVT_SHAKE 11

#define MICROBIT_BUTTON_EVT_DOWN 1
#define MICROBIT_BUTTON_EVT_UP 2
#define MICROBIT_BUTTON_EVT_CLICK 3
#define MICROBIT_BUTTON_EVT_LONG_CLICK 4
#define MICROBIT_BUTTON_EVT_HOLD 5
#define MICROBIT_BUTTON_EVT_DOUBLE_CLICK 6

#define MICROBIT_RADIO_EVT_DATAGRAM 1
```



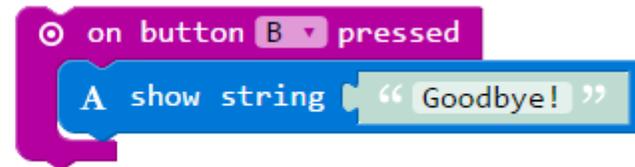
micro:bit runtime architecture



Fiber Scheduler: Providing Concurrent behaviour...

...or at least *apparently* concurrent behaviour!

- Take this simple example again. What behaviour would you expect?
- Given that show string will scroll the given text on the 5x5 matrix display...



Fiber Scheduler: Providing Concurrent behaviour..

- Fibers can be created at any time, and execute independently
- By design, a **non pre-emptive** scheduler to reduce potential race conditions.
- Fibers can sleep, or block on events on the MessageBus
- Anytime there's nothing to do... processor enters a power efficient sleep

```
void doSomething()  
{  
    while(1)  
    {  
        uBit.display.print('A');  
        uBit.sleep(100);  
    }  
}
```

```
void doSomethingElse()  
{  
    while(1)  
    {  
        uBit.display.print('B');  
        uBit.sleep(100);  
    }  
}
```



Fiber Scheduler: Providing Concurrent behaviour...

- A **RAM optimised** thread scheduler for Cortex processors.
- We adopt a stack duplication approach
- Keeps RAM cost of fibers low, at the expense of CPU time
- Each fiber typically costs ~200 bytes.
- Event handlers (by default) run in their own fiber*
- Effectively decoupling kids' code from nasty interrupt context code.
- Functions (e.g. scroll text) can block the calling fiber until the task completes...
- ...and event handlers can safely execute users code without risk of locking out the CPU...
- ...so our blocks program can simply and efficiently translate to this:



Fiber Scheduler: Providing Concurrent behaviour..

```
void onButtonA()
{
    uBit.display.scroll("hello");
}

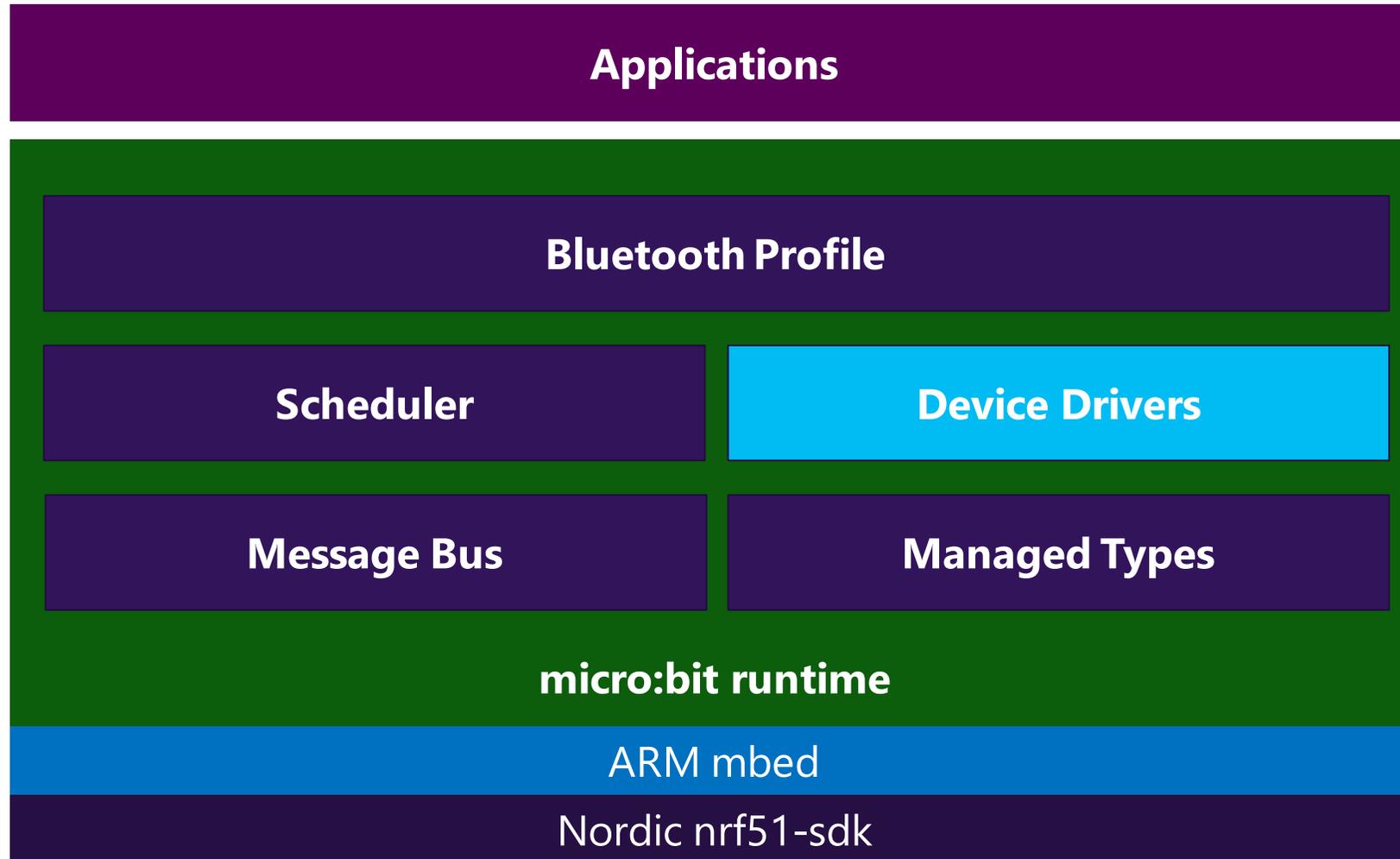
void onButtonB()
{
    uBit.display.scroll("goodbye");
}

// Then in your main program...

uBit.messageBus.listen(MICROBIT_ID_BUTTON_A, MICROBIT_BUTTON_EVT_CLICK, onButtonA);
uBit.messageBus.listen(MICROBIT_ID_BUTTON_B, MICROBIT_BUTTON_EVT_CLICK, onButtonB);
```



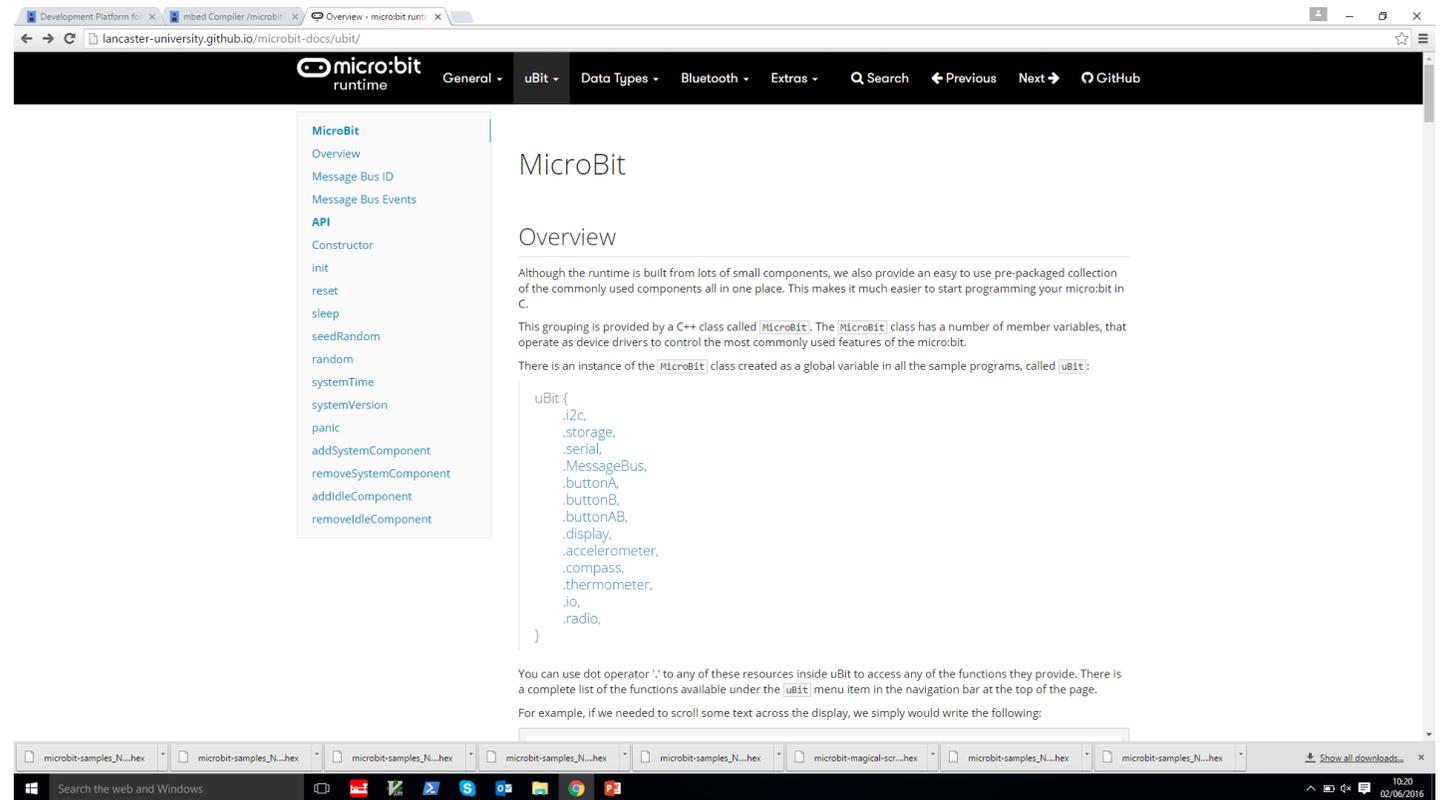
micro:bit runtime architecture



Device Drivers

- Each hardware component is supported by a corresponding C++ software component:

- MicroBitAccelerometer
- MicroBitButton
- MicroBitMultiButton
- MicroBitCompass
- MicroBitDisplay
- MicroBitIO
- MicroBitLightSensor
- MicroBitRadio
- MicroBitSerial
- MicroBitStorage
- MicroBitThermometer



The screenshot shows a web browser displaying the documentation for the micro:bit runtime. The page title is "MicroBit" and the sub-section is "Overview". The navigation bar includes "General", "uBit", "Data Types", "Bluetooth", "Extras", "Search", "Previous", "Next", and "GitHub". The left sidebar lists the "API" section with various methods like "init", "reset", "sleep", "seedRandom", "random", "systemTime", "systemVersion", "panic", "addSystemComponent", "removeSystemComponent", "addIdleComponent", and "removeIdleComponent". The main content area explains that the runtime is built from small components and provides a pre-packaged collection of commonly used components. It mentions a C++ class called `MicroBit` and an instance of it called `uBit`. A code snippet shows the `uBit` class structure with member variables like `.i2c`, `.storage`, `.serial`, `.MessageBus`, `.buttonA`, `.buttonB`, `.buttonAB`, `.display`, `.accelerometer`, `.compass`, `.thermometer`, `.io`, and `.radio`. The page also notes that the dot operator `!` can be used to access these resources.

Device Drivers

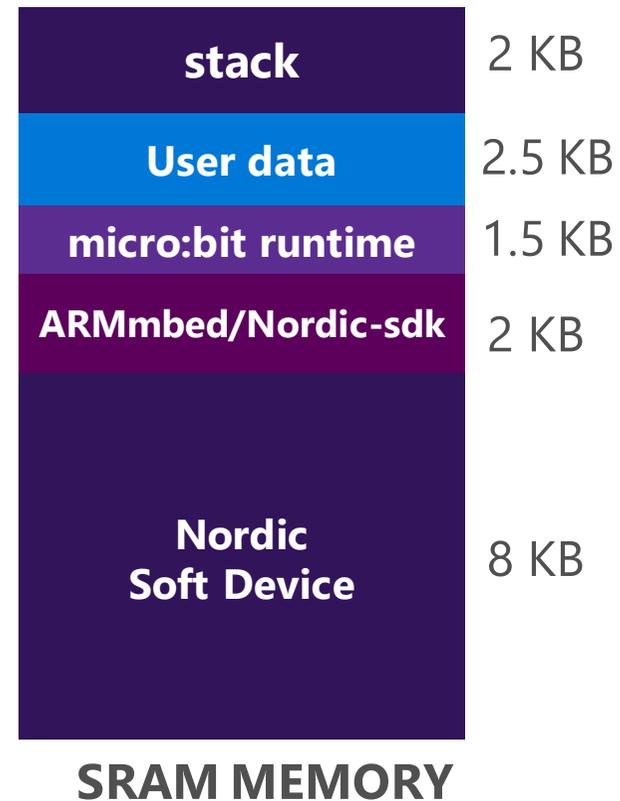
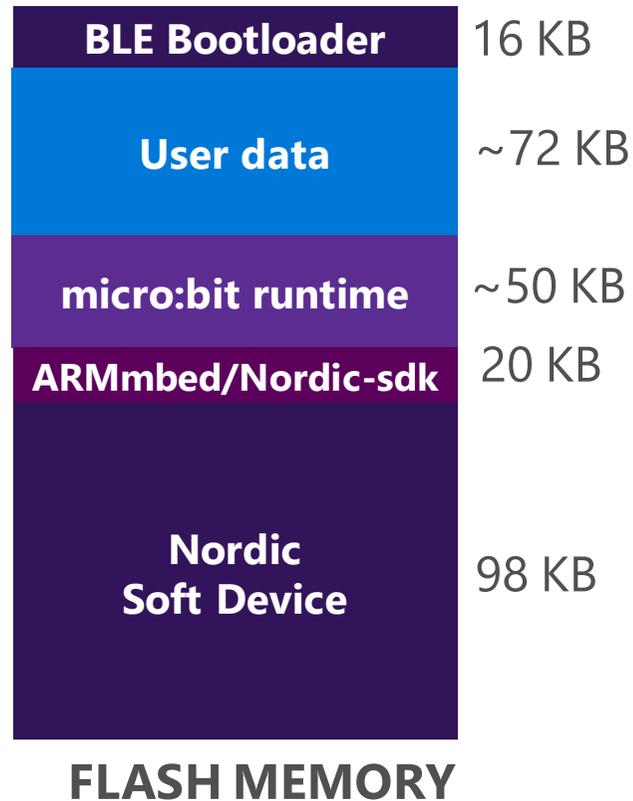
- Complexity of fine grained initialization too great for most high level languages...
- So we wrap the common set of components together:

```
MicroBit uBit;  
  
int main()  
{  
    // initialise runtime  
    uBit.init();  
  
    // code!  
    uBit.display.scroll("Hello World!");  
}
```



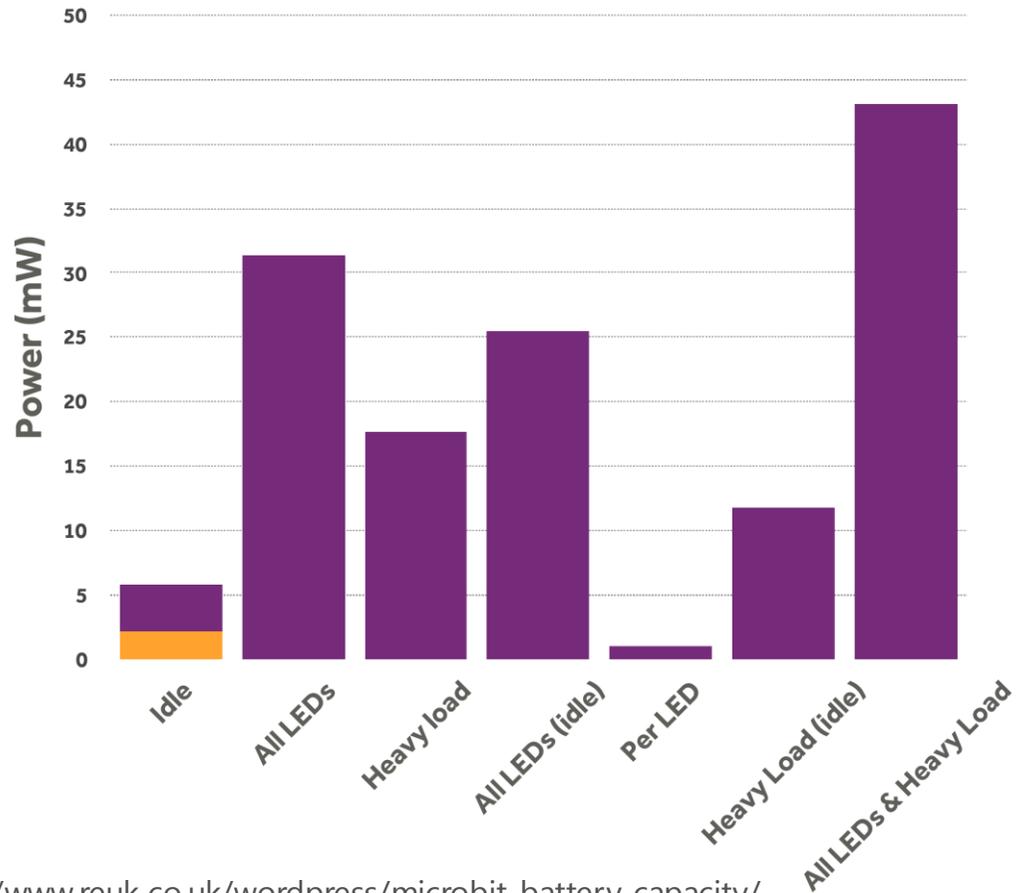
Memory Footprint

- micro:bit has 16Mhz Nordic nrf51822 CPU (32 bit Cortex M0)
- 256 KB FLASH memory, 16KB SRAM...



Power Efficiency

Power consumed at 3 Volts



Pi 3 ~ 2000mW

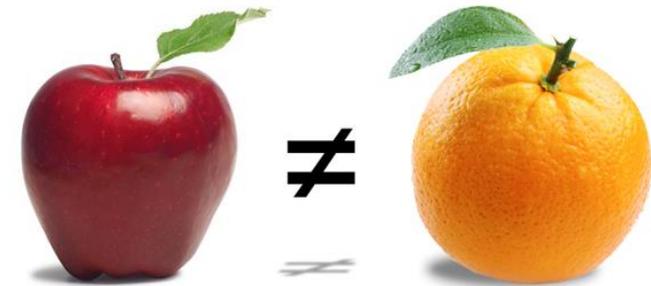
<https://www.raspberrypi.org/help/faqs/>

Pi Zero ~500mW

<http://raspi.tv/2015/raspberry-pi-zero-power-measurements>

Arduino Uno ~400mW

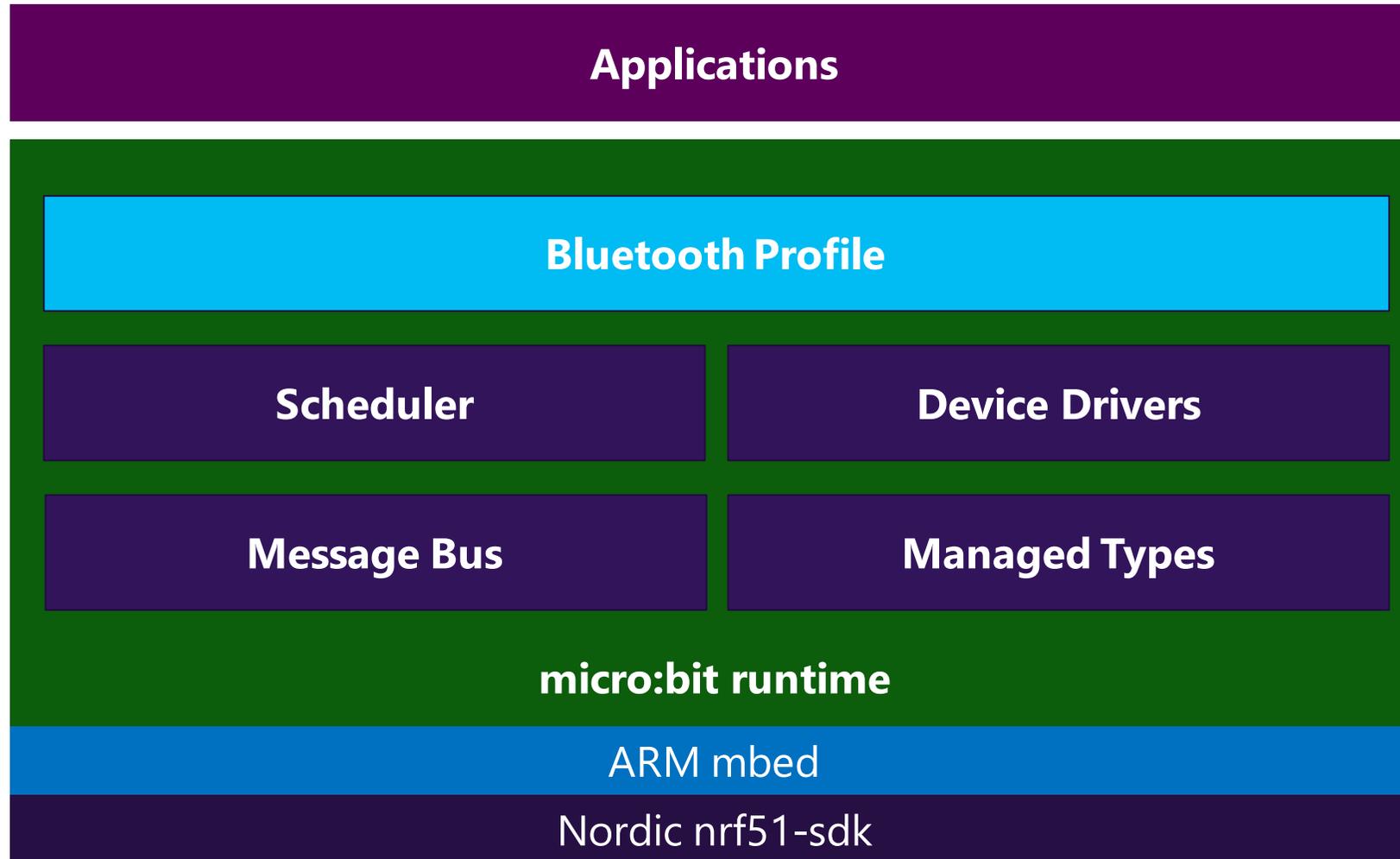
<http://forum.arduino.cc/index.php?topic=135872.0>



<http://www.reuk.co.uk/wordpress/microbit-battery-capacity/>



micro:bit runtime architecture

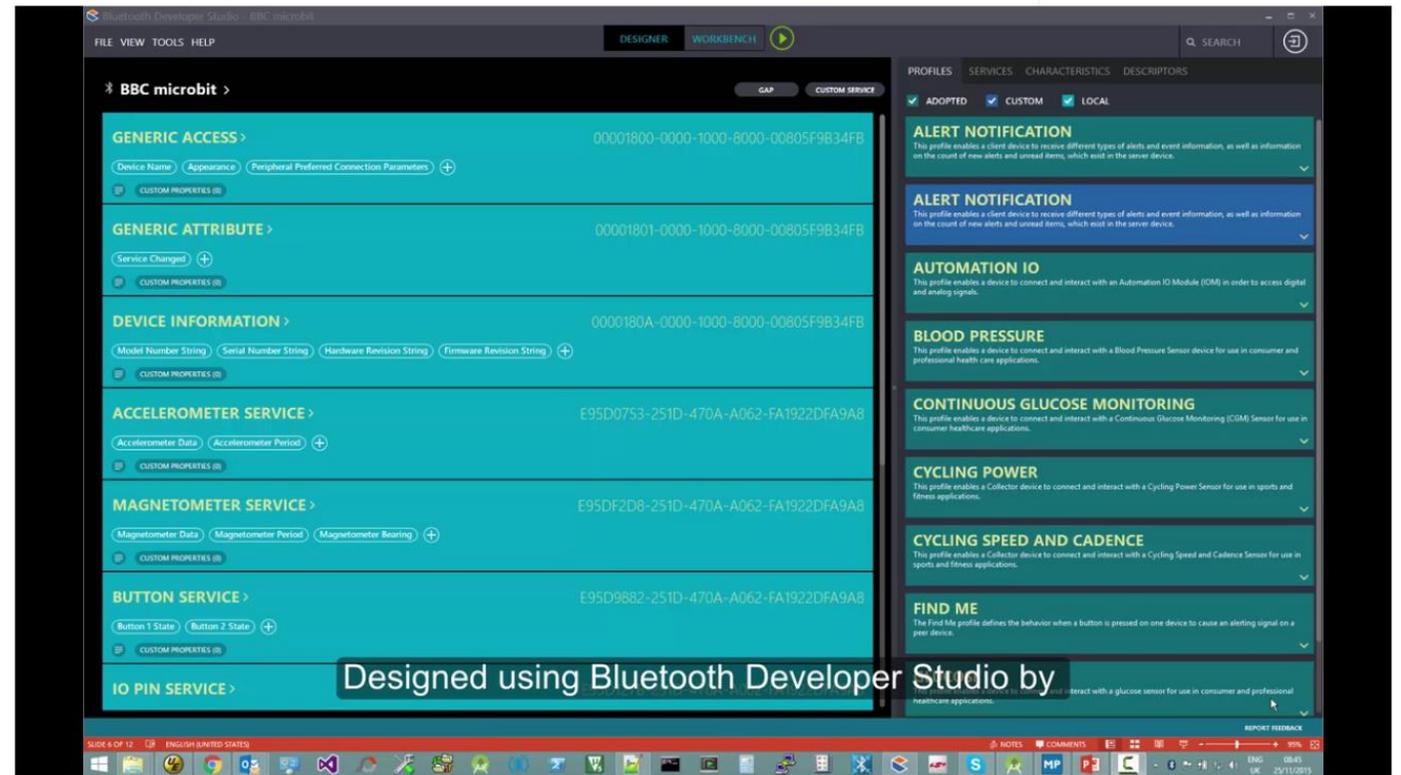


Bluetooth Profile

- Each driver component also mapped as RESTful Bluetooth API...

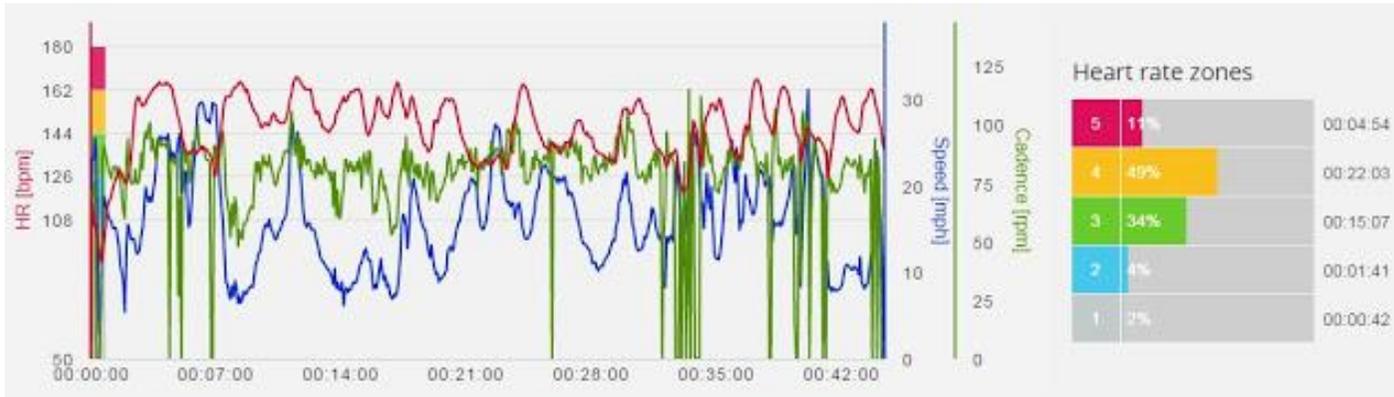
- MicroBitAccelerometerService
- MicroBitButtonService
- MicroBitMagnetometerService
- MicroBitLEDService
- MicroBitIOPinService
- MicroBitTemperatureService
- MicroBitEventService
- UARTService
- DeviceFirmwareUpdate

- Keyboard HID (coming soon)
- iBeacon/Eddystone (coming soon)



microbit_profile_overview from Martin Woolley on Vimeo.

Bluetooth Profile



© Martin Woolley Bluetooth SIG



@microbitruntime @bluetooth_mdw
@duncancragg Support for controlling one from Node.js (OS X, Linux) is out:



<http://bluetooth-mdw.blogspot.co.uk/p/bbc-microbit.html>
<https://play.google.com/store/apps/details?id=com.bluetooth.mwoolley.microbitbledemo>



MicroBitRadio

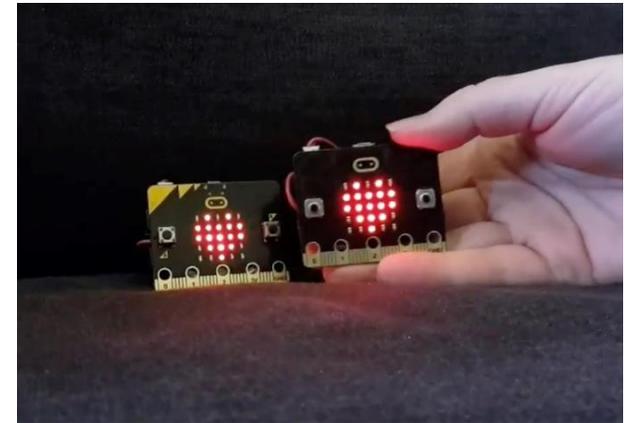
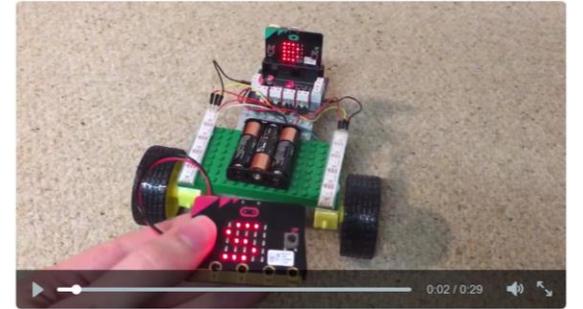
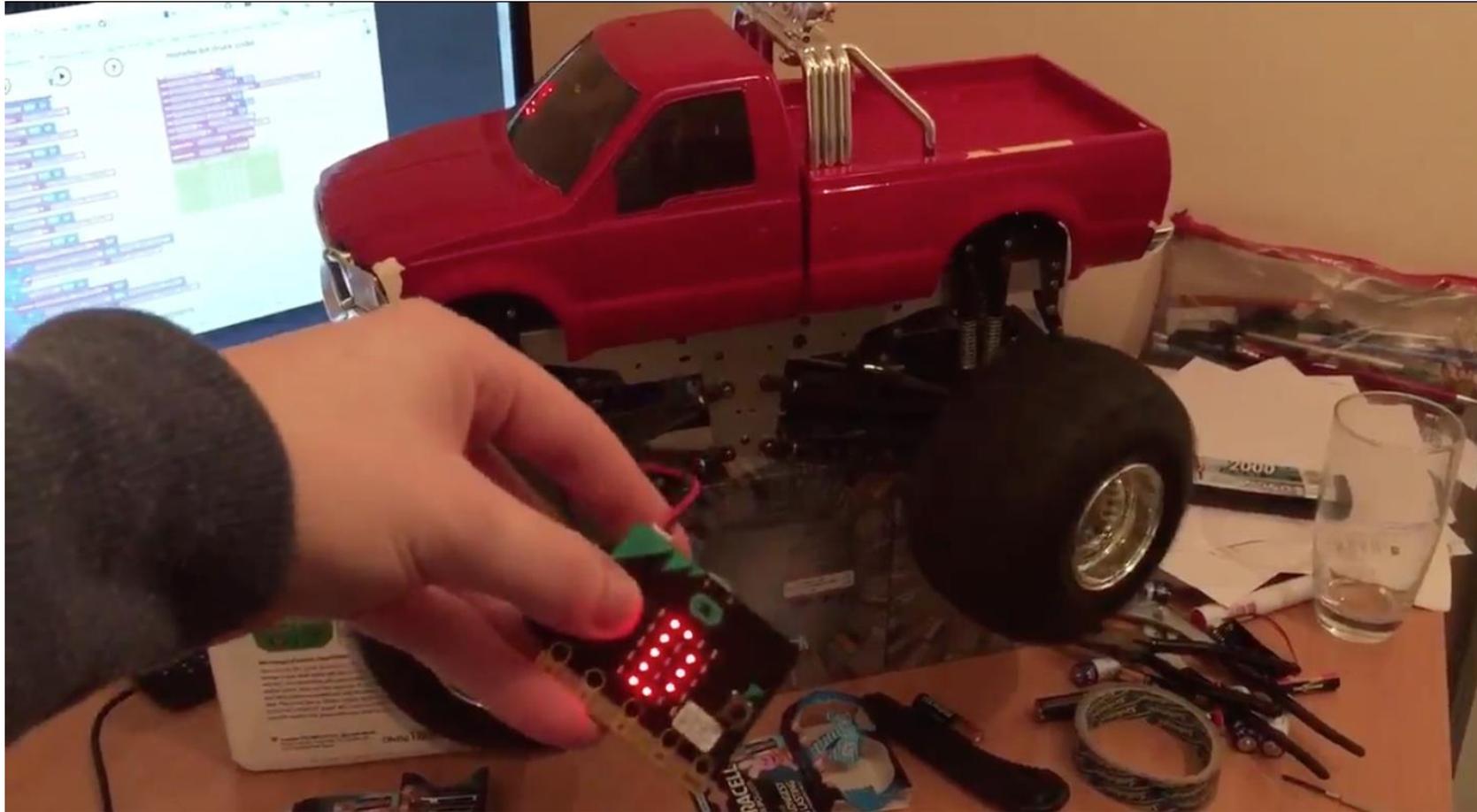
Simple, raw packet communications...

```
forever
  if acceleration (mg) x < -250
  do set steeringCommand to STEERING_CMD_LEFT
  else if acceleration (mg) x > 250
  do set steeringCommand to STEERING_CMD_RIGHT
  else set steeringCommand to STEERING_CMD_MIDDLE
  send number steeringCommand
  pause (ms) 100
```

```
on data received
do set receivedVal to receive number
  if receivedVal = 0
  do set steering to STEERING_LEFT
  else if receivedVal = 1
  do set steering to STEERING_RIGHT
  else if receivedVal = 2
  do set steering to STEERING_MIDDLE
  servo write acceleration to pin P0
  servo write steering to pin P1
```



MicroBitRadio



Coming soon to a micro:bit near you

- Features currently under development...
 - On chip file system, exposed through USB interface
 - End-to-end IoT interfaces
 - Platform independence





Wanna go
play?

<http://lancaster-university.github.io/microbit-docs/>

<https://developer.mbed.org/platforms/Microbit/>

<https://codethemicrobit.com/>

<https://www.microbit.co.uk/>

 @microbitruntime

 lancaster-university/microbit-dal

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