

# Stacked Ensembles of Information Extractors for Knowledge-Base Population

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# Knowledge-Base Population (KBP)

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- Annual evaluation of relation extraction from natural language documents organized by NIST.
- English Slot Filling (ESF) task:

<b>per: Barack Obama</b>
<b>country_of_birth</b> United States
<b>spouse</b> Michelle Obama
<b>children</b> Malia Obama Sasha Obama

<b>org: Microsoft</b>
<b>city_of_headquarters</b> Redmond
<b>website</b> microsoft.com
<b>subsidiaries</b> Skype Nokia

# KBP Provenance

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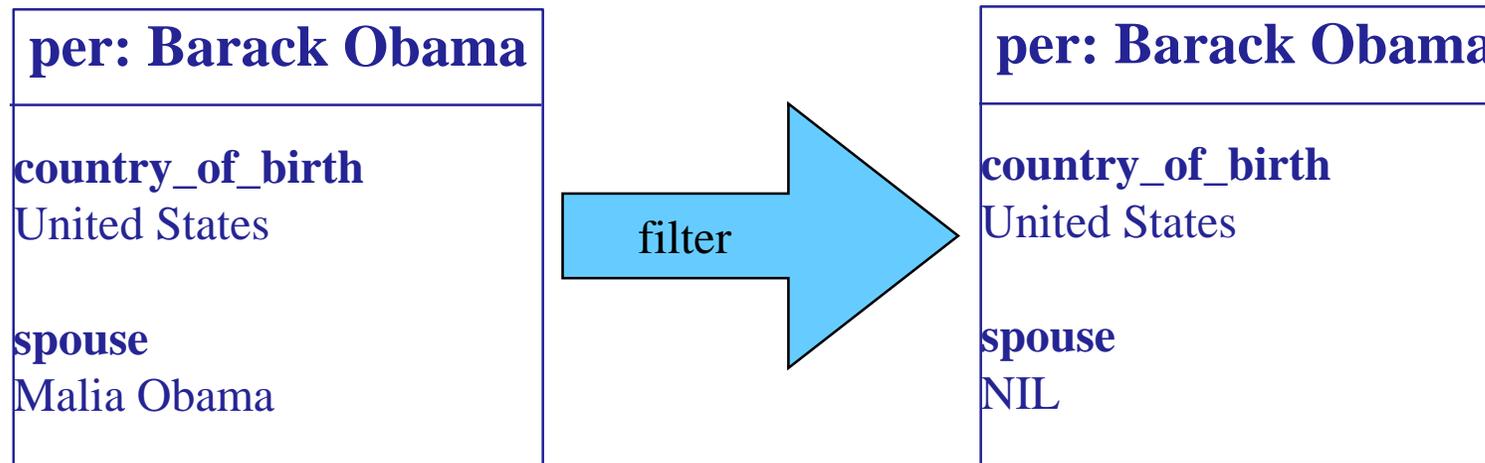
- System's must provide information on where the evidence for each slot fill is in the document corpus.
- Given by:
  - Doc ID
  - Start Offset
  - End Offset

<b>org: Microsoft</b>
<eng-NG-31-1007>: Microsoft is a technology company headquartered in Redmond, Washington, that develops ...
<b>city_of_headquarters</b> Redmond <b>Doc ID</b> eng-NG-31-1007 <b>Start Offset</b> 48 <b>End Offset</b> 54

## KBP Slot Filler Validation

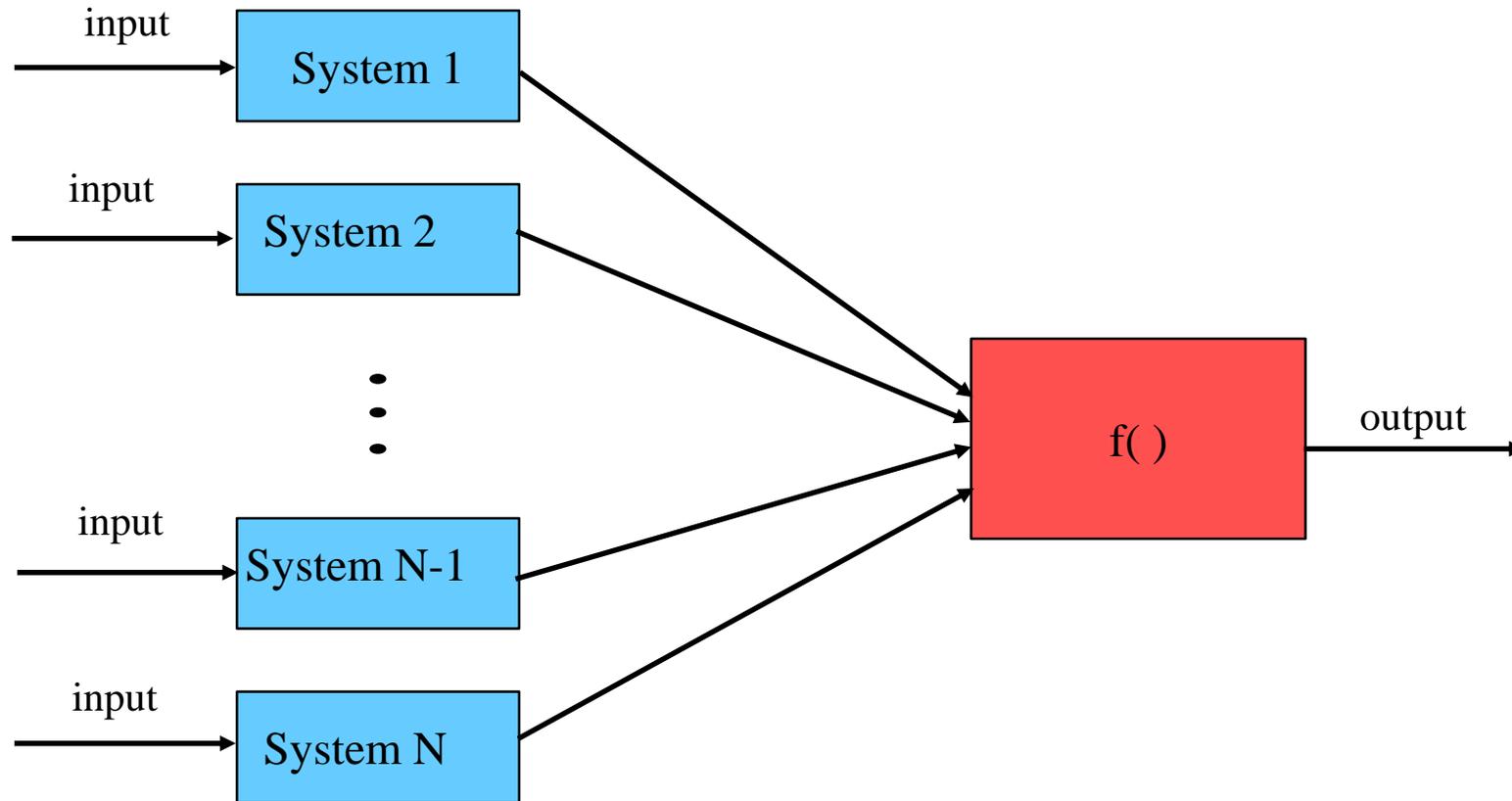
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- Aim: Improve precision of individual systems.
- Input is system outputs from the ESF task.
- Output is filtered slot fills.
- Ensembling used to improve recall as well.



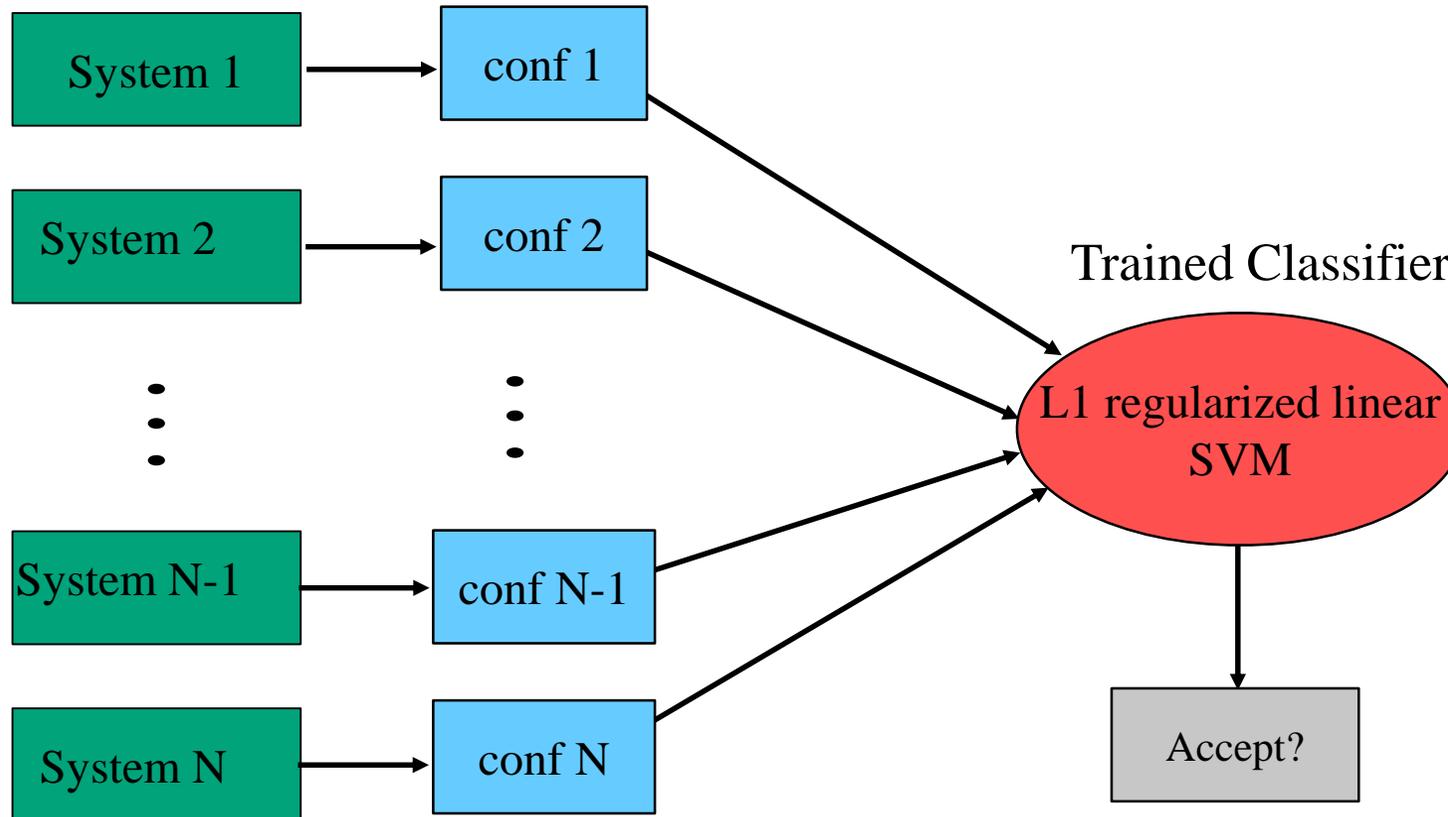
## Ensembling

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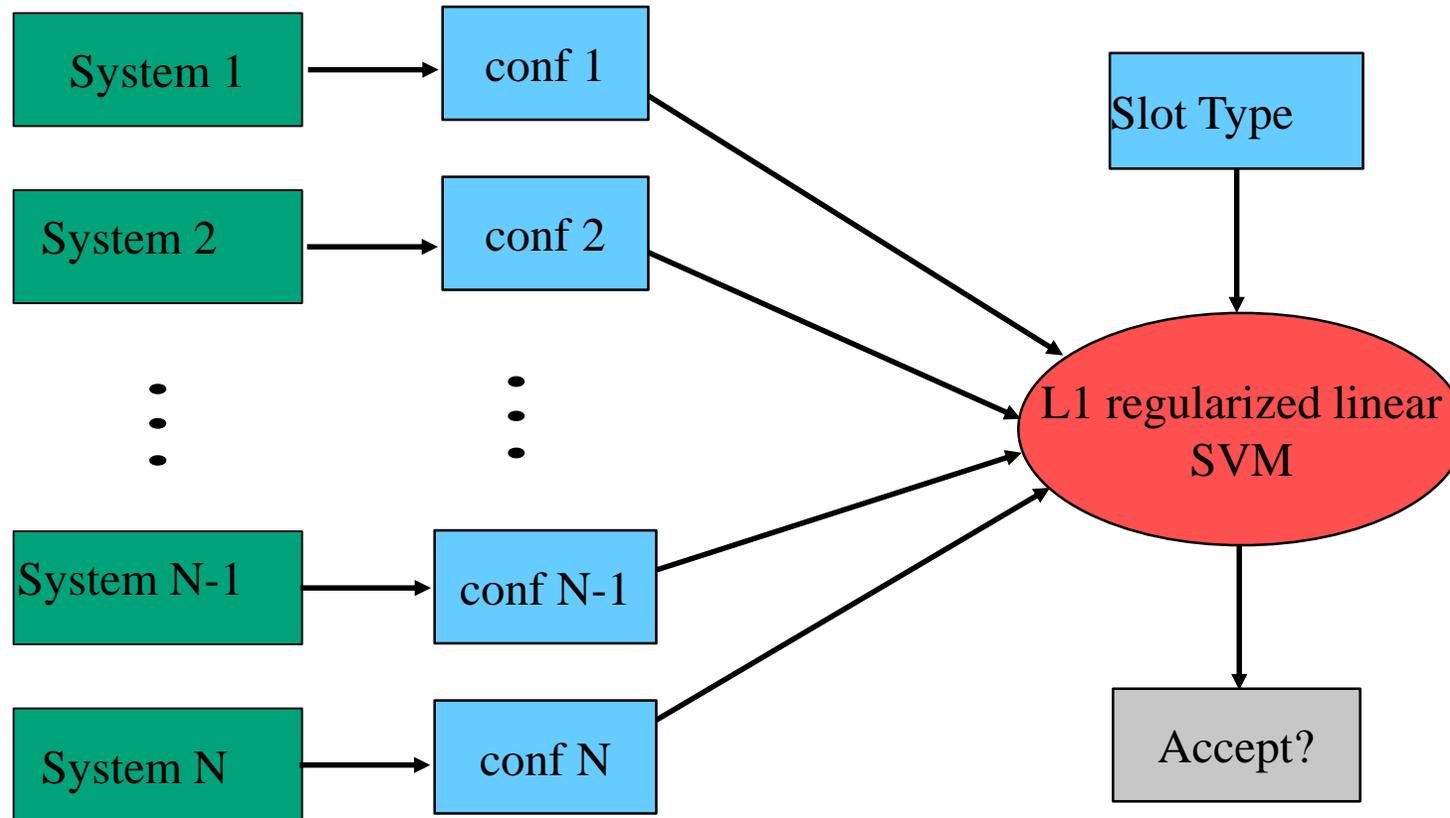
## Stacking (Wolpert, 1992)

For a given proposed slot-fill, e.g. spouse (Barak, Michelle), combine confidences from multiple systems:



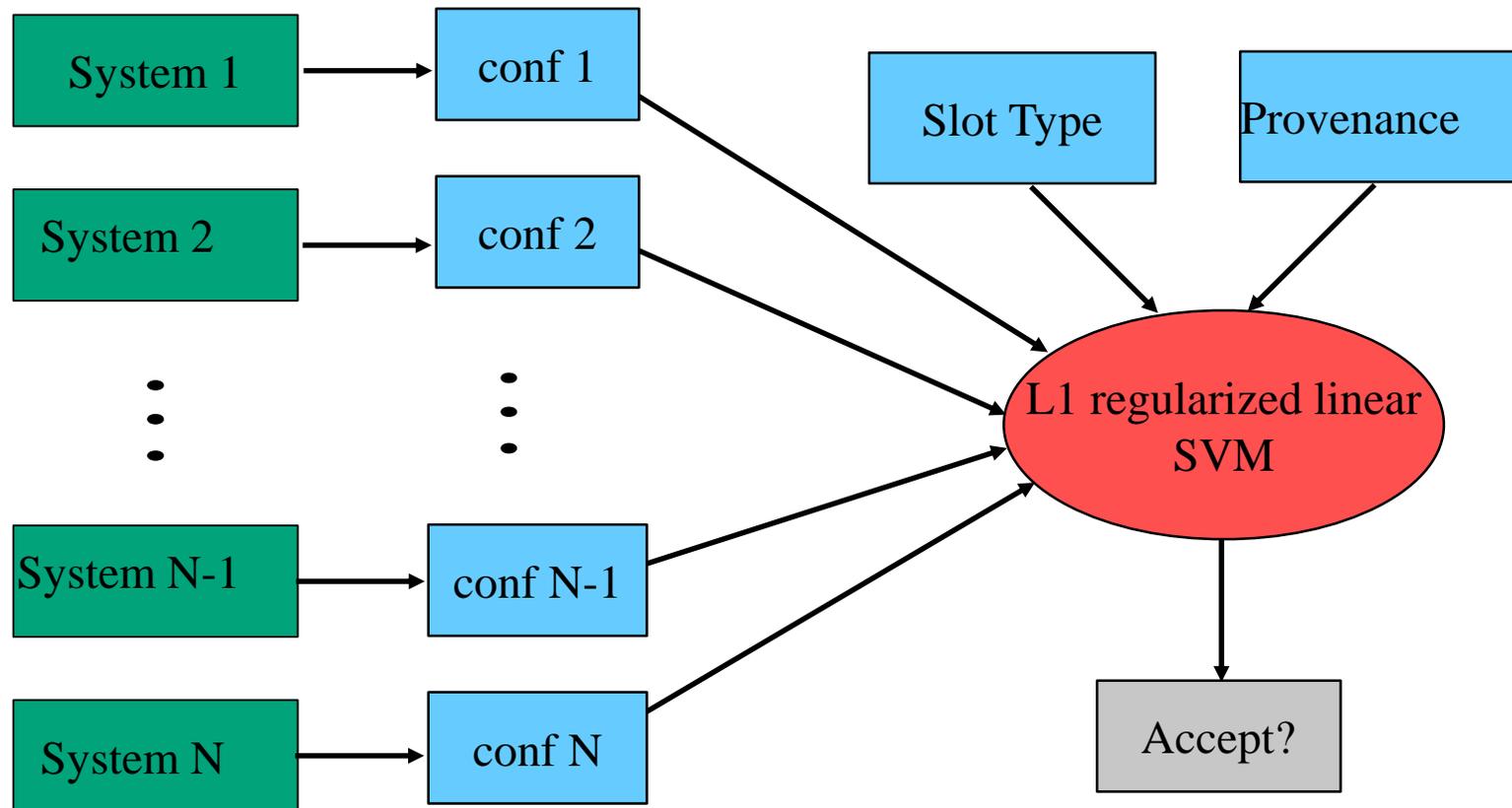
## Stacking with Features

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## Stacking with Features

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## Document Provenance Features

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- For a given query and slot, for each system,  $i$ , there is a feature  $DP_i$ :
  - $N$  systems provide a fill for the slot.
  - Of these,  $n$  give same provenance *docid*.
  - $DP_i = n/N$  is the document provenance score.
- Measures extent to which systems agree on document provenance of the slot fill.

## Offset Provenance Features

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- Degree of overlap between systems' provenance strings (prov).
- Uses Jaccard similarity coefficient.
- For a given query and slot, for each system,  $i$ , there is a feature  $OP_i$ :
  - $N$  systems provide a fill with same *docid*
  - Offset provenance for a system  $i$  is calculated as:

$$OP_i = \frac{1}{|N|} \times \sum_{j \in N, j \neq i} \frac{|\text{prov}(i) \cap \text{prov}(j)|}{|\text{prov}(i) \cup \text{prov}(j)|}$$

- Systems with different *docid* have zero OP

- Ten Common Systems that participated both in 2013 and 2014:
  - LSV
  - IIRG
  - UMASS\_IESL
  - Stanford
  - BUPT\_PRIS
  - RPI\_BLENDER
  - CMUML
  - NYU
  - Compreno
  - UWashington
- 2014 Slot Filler Validation data
  - 17 teams
  - 65 systems

## Baselines

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- **Union**
  - Combine systems for maximizing recall
  - List valued slot fills => always included
  - Single valued slot fills => highest confidence
- **Voting**
  - Combine systems for maximizing precision
  - Vary threshold on #systems that must agree
  - Learn threshold on 2013 data
  - SFV and common systems datasets

## KBP English Slot Filling Results

2014 Slot Filler Validation (SFV) Data

<b>Baseline</b>	<b>Precision</b>	<b>Recall</b>	<b>F1</b>
Union	0.067	<b>0.762</b>	0.122
Voting	<b>0.641</b>	0.288	<b>0.397</b>

Common systems for 2013 and 2014 ESF task

<b>Approach</b>	<b>Precision</b>	<b>Recall</b>	<b>F1</b>
Union	0.176	<b>0.647</b>	0.277
Voting	<b>0.694</b>	0.256	0.374
Best ESF system in 2014 (Stanford)	0.585	0.298	0.395
Stacking	0.606	0.402	0.483
Stacking + Relation	0.607	0.406	0.486
Stacking + Provenance + Relation	0.541	0.466	<b>0.501</b>

## KBP Slot Filler Validation Results

2014 Slot Filler Validation (SFV) Data

<b>Baseline</b>	<b>Precision</b>	<b>Recall</b>	<b>F1</b>
Union	0.054	<b>0.877</b>	0.101
Voting	<b>0.637</b>	0.406	<b>0.496</b>

Common systems for 2013 and 2014 ESF task

<b>Approach</b>	<b>Precision</b>	<b>Recall</b>	<b>F1</b>
Union	0.177	<b>0.922</b>	0.296
Voting	<b>0.694</b>	0.256	0.374
Best SFV system in 2014 (UIUC)	0.457	0.507	0.481
Stacking	0.613	0.562	0.586
Stacking + Relation	0.613	0.567	0.589
Stacking + Provenance + Relation	0.659	0.56	<b>0.606</b>

## Conclusion

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- Stacked meta-classifier beats the best performing 2014 KBP ESF system by an F1 gain of **11** points.
- Features that utilize provenance information improve stacking performance.
- Ensembling has clear advantages but naive approaches such as voting do not perform as well.